

CCGS Amundsen 2010 Field Program ArcticNet / BP Partnership Met/Ocean Data Report



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ArcticNet
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Executive Summary

This document details datasets collected by researchers based at the Centre for Earth Observation Science (CEOS), University of Manitoba, under the Met/Ocean and Sea Ice component of the ArcticNet / Industrial Partnership during the 2010 field season. Our group is actively involved in research that revolves around improving our understanding of coupled processes between the ocean, sea ice, and atmosphere, as well as how this coupling impacts the ecology of the sea ice, and the waters immediately beneath. We employ a large ensemble of ship-based sensors, and physical sampling equipment that collect large volumes of data from the atmosphere, ocean, and sea ice. Our data collection efforts are driven by many interlinked objectives. Objectives relevant to our partnership with BP Exploration Operating Company Ltd. (hereafter referred to as 'BP'), and corresponding data collection during 2010 are as follows:

- 1) **Ocean:** Describe the nature of currents, salinity, temperature, and associated physical variables in the southern Beaufort Sea, and over the BP lease blocks (Pokak).
- 2) **Sea Ice:** Describe the aerial concentration, type, growth history, strength and periodicity of sea ice in the southern Beaufort Sea, and over Pokak.
- 3) **Atmosphere:** Describe the magnitude and variability of key meteorological variables over the ocean and relative to adjacent land stations.
- 4) **Coupling:** Provide data on the key coupling mechanisms across the ocean-sea ice-atmosphere (OSA) interface with a particular emphasis on fluxes of mass, energy and momentum.

Field research and data collection activities relevant to these objectives were conducted from the Canadian Coast Guard research icebreaker *Amundsen* (hereafter referred to as "CCGS *Amundsen*"), from 12 August to 07 October 2010, our group conducted a variety of sampling activities in the Southern Beaufort Sea, and within the Pokak Block including, but not limited to: aerial ice thickness surveys passive and active microwave scanning of sea ice, buoy deployment (one surface buoys, one ice mass balance buoy, 13 position-only drift buoys), synoptic meteorology (22 weather balloons, atmospheric profiling, cloud type and coverage), and micrometeorology (radiation, *in situ* meteorology), and ocean sampling (roughness, currents, conductivity-temperature-density profiling).

ArcticNet 2010 Data Use Policy

All data described in the document hereafter was collected during the 2010 ArcticNet / BP partnership field season. The Centre for Earth Observation Science shall make all datasets available upon request to BP, pending resolution of quality-assurance related issues. Updates to datasets will be made available to BP as they become available.

All other data access requests shall be addressed to Dr. David Barber at the Centre for Earth Observation Science, University of Manitoba (dbarber@cc.umanitoba.ca). CEOS retains exclusive rights to all data collected during the field season. Field members have first rights to the data for a period of 2 years, followed by non-field participants. Please reference use of any material in this report as follows:

Section 5.4. Cloud Base Height, *in* Asplin M. and Galley, R., (Eds.) *CEOS-TEC-2011-01-31. pp. 84 - 86.*

Acknowledgements

First and foremost, we would like to acknowledge the support and expertise of the hardworking crews of the Research Icebreaker CCGS *Amundsen*. Our sincere gratitude is extended to Captains Stéphane Julien, and Marc Thibault. Their patience and expertise was paramount to the success of the 2010 partnership field season.

We would like to acknowledge BP for graciously providing funding for the 2010 ArcticNet Cruise, and for the Met/Ocean team's operations and equipment. This represents an ongoing successful and productive Arctic research and discovery partnership between industry and ArcticNet.

We are indebted to Keith Levesque, ArcticNet's shipbased research coordinator, for his tireless efforts, dedication and investment in the preparation of this very challenging 2010 expedition. From community consultations, to research licensing, to planning workshops, to ship mobilization, crew changes, security clearances and the numerous needs of dozens of demanding research groups rotating onboard the ship, a colossal amount of work is involved in the preparation of such an expedition. Thanks to Keith and all who helped him with the preparation of this 2010 expedition.

We would also like to thank Martin Fortier, executive director of ArcticNet, for his dedication to ArcticNet, and in particular for the support and energy that he extended toward the planning and implementation of the 2010 field season. Last but not least, we would also to acknowledge his contributions to the field season overview in this data report (section 1.1).

Several government agencies contributed to the success of the 2010 ArcticNet / BP partnership field season in the Southern Beaufort Sea. These include the Natural Sciences and Engineering Council (NSERC), the Canada Research Chairs Program (CRC), the Networks of Centres of Excellence Program (NCE), Northern Scientific Training Program (NSTP), Department of Indian and Northern Affairs Canada (INAC), the Canadian Ice Service (CIS), the Canadian Space Agency (RADARSAT-1, RADARSAT-2), the European Space Agency (ESA), the National Aeronautics and Space Administration (NASA), Environment Canada (EC), the Meteorological Service of Canada (MSC), the Department of Fisheries and Oceans (DFO), and the Canadian Coast Guard Service (CCGS).

Title page photo credit: Travis Hamilton, University of New Brunswick Ocean Mapping Group

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SECTION ONE: INTRODUCTION

1.1 Preface

The Beaufort Sea/Mackenzie Shelf region of the Arctic Ocean has witnessed major changes in recent years, with decreasing sea ice cover and major shifts in sea-ice dynamics. Although major inshore research activities were conducted in the 70's and 80's in large part due to the Oil & Gas interest in the regions, much less is known about the offshore region of the Mackenzie Shelf, shelf slope and Beaufort Sea. Recent interest in the Beaufort Sea has resulted in major bids from industry on offshore exploration licenses (EL) located in the 50 – 1500 m depth range of the shelf and shelf break. Of particular relevance to the 2010 expedition is EL449 (called Pokak) which is owned by BP (see Figure 1).

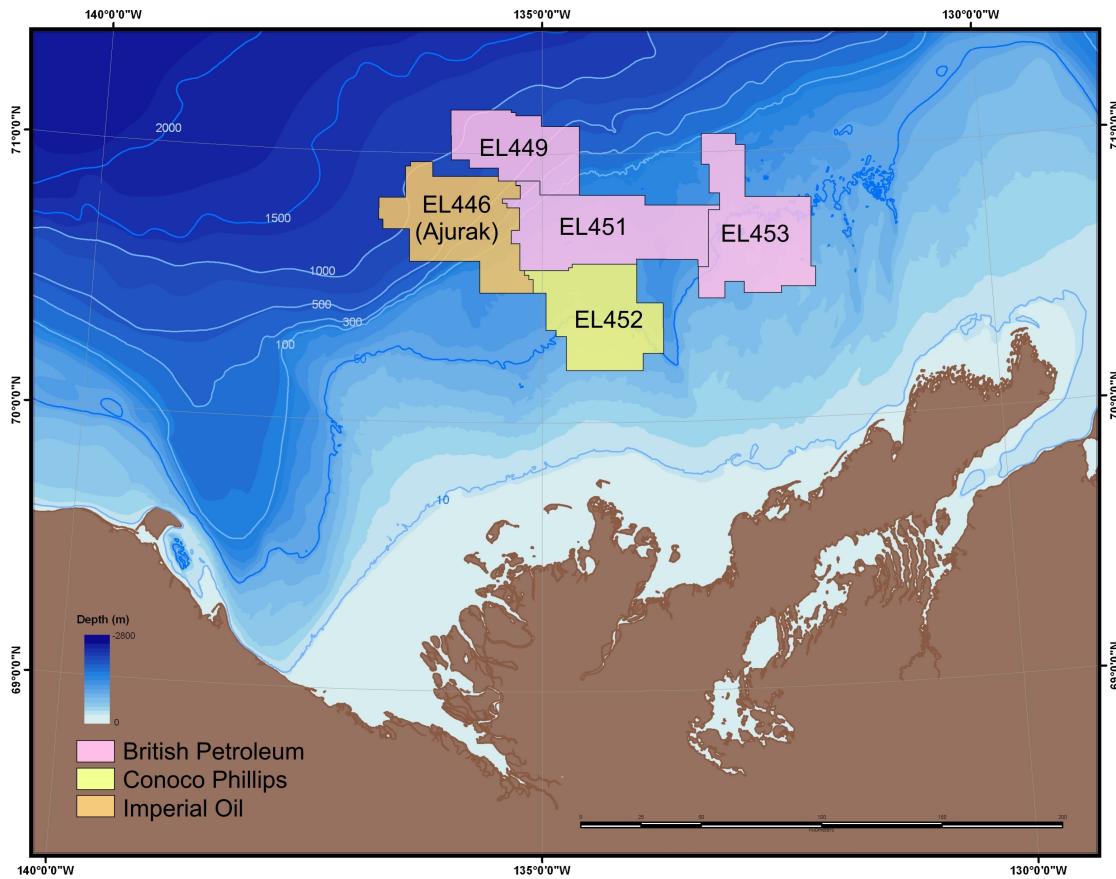


Figure 1: Map of offshore Exploration Licenses (EL) awarded by the Department of Indian and Northern Affairs in 2007 and 2008 (modified from image courtesy of Geological Survey of Canada).

Since 2002, ArcticNet has been conducting extensive multidisciplinary research programs in the area. In addition to an annual fall sampling program, ArcticNet researchers have led two major international overwintering research programs conducted onboard the CGGS *Amundsen* in 2003-2004 ([CASES program](#)) in 2007-2008 ([CFL program](#)) (Barber et al., 2010), and for the 2009 survey of the Ajurak Block (EL452, Figure 1), a lease owned by Imperial Oil Ltd. A marine observatory of a minimum of 5 oceanographic annual moorings (from 5 to 17 moorings) has been deployed and retrieved annually in the area by ArcticNet researchers since 2002.

During the summer of 2010, the CCGS *Amundsen* was the platform for field research conducted under ArcticNet, and the partnership between BP and Imperial Oil Resource Ventures Ltd (IORVL). This partnership not only forms an important link between industrial and scientific initiatives, but also has enabled continued monitoring and sampling activities in the Western Canadian Arctic.

The Partnership has been established as the result of the concurrent need for resources and research within the offshore Northern Oil and Gas lease regions. Under the agreement, BP will provide operating and logistic financial support for the CCGS *Amundsen*, and will allow for the consolidation of environmental and risk-assessment research efforts. Active ArcticNet sampling programs, such as ice geophysics and dynamics, ice distribution and thickness and bottom mapping, are of particular interest to BP for the reasoning and development of potential future offshore drilling platforms in the Southern Beaufort Sea. The CCGS *Amundsen* cruise sampling timeline for 2010 is organized into segments, referred to as 'legs.' A summary of the legs is provided in Table 1.

Table 1: Summary of CCGS *Amundsen* 2010 Legs.

LEG	Start	Finish	Program	Sampling Area
Leg 1a	03 July	02 Aug	ArcticNet	Hudson Bay ArcticNet Program
Leg 1b	02 Aug	12 Aug	ArcticNet	Baffin Island, NW Passage Transit
Leg 2a	12 Aug	26 Aug	ArcticNet / BP Partnership	Southern Beaufort Sea (Pokak Block)
Leg 2b	26 Aug	23 Sept	ArcticNet / BP Partnership	Southern Beaufort Sea (Pokak Block)
Leg 3a	23 Sept	07 Oct	ArcticNet / BP Partnership	Beaufort Sea (transect into the pack ice)
Leg 3b	07 Oct	22 Oct	ArcticNet	NW Passage, Baffin Bay, Iqaluit
Leg 3c	22 Oct	02 Nov	ArcticNet	Labrador Fjords

As part of a collaborative agreement between ArcticNet and BP, one of the major goals of the 2010 ArcticNet expedition to the western Arctic was to increase the level and spatial coverage of sea-ice, geological and environmental data collected by the ArcticNet network in the Beaufort Sea/Mackenzie Shelf/Amundsen Gulf region (regional context) with a special focus placed in and around the Pokak lease area.

As designed jointly by ArcticNet and BP, the research elements of the collaborative work are divided into three major research components:

1) Met/Ocean & Sea Ice Component: The overarching goal of this component is to provide data that describe the variability of met/ocean and sea ice variables within the Pokak exploration block relative to the larger area of the southern Beaufort Sea continental shelf. The objective is to provide data on the ocean-sea ice-atmosphere (OSA) interface over a range of time and space scales, focusing on spatial and temporal variability over diurnal, seasonal and interannual time scales.

2) Environment & Marine Resources Component: The general goal of this component is to quantify and map the summer-fall distribution and contamination of the main compartments of the pelagic and benthic food webs along the slope of the Mackenzie Shelf, from the inner shelf (50 m) to the margin of the deep basin (approx. 1200 m), and from the Mackenzie Trough to the west to Cape Bathurst to the east with special focus on specific areas in Pokak.

3) Geology/ Bathymetry Component: This component will conduct an investigation of seabed stability conditions to meet engineering design and regulatory requirements for exploration drilling. Seabed mapping and bottom sediment characterization research is required to investigate seafloor stability conditions at the outer shelf/upper slope area of the central Beaufort Sea with special focus on specific areas in Pokak. Foundation conditions, slope stability, seabed features and ice scouring are also key issues to be addressed.

This data report is intended to describe and summarize datasets collected by the scientific team based at the Centre for Earth Observation Science, University of Manitoba (herein the “Met/Ocean Team”) for field activities conducted between 12 August and 07 October 2010, which spans Leg 2A, 2B and 3A of the 2010 cruise of the CCGS *Amundsen*.

1.2 The Met/Ocean Team

The Principal Investigators of the Met/Ocean team are:

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The Met/Ocean team is comprised of multi-disciplinary research associates, technicians, and graduate students who are based at CEOS, University of Manitoba. These individuals were dedicated to one (or more) of the eight disciplinary Met/Ocean teams: Surface Buoys, Ocean and Sea Ice Optics, Surface Roughness, Helicopter Electromagnetic Induction Surveys (HEMI), Remote Sensing, Sea Ice Physics, Micrometeorology, and Synoptic Meteorology. Team members were tasked with sampling activities, based upon sampling priorities established for each leg of the cruise. Table 2 provides a summary of the sampling priority for each of the disciplines for the cruise schedule, as some legs will favor some groups over others depending on data collection priorities and sea ice conditions.

Table 2: Met/Ocean science priorities by leg

Leg	GROUPS
2A	HEMI Ice Surveys, Surface Buoys, Micrometeorology, Meteorology
2B	Micrometeorology, Meteorology
3A	HEMI Ice Surveys, Micrometeorology, Meteorology, Remote Sensing, Sea Ice Physical Sampling, Ice Mass Balance Buoy deployment

1.3 Data Report Outline

Section 1 provides a brief introduction to the partnership between ArcticNet and BP, and sets the context for the report.

Section 2 summarizes the mobilization, crew changes, transit, and science activities of the CCGS *Amundsen*'s 2010 field season as conducted.

Sections 3, 4 and 5 present a detailed summary of ocean, sea ice, and meteorology datasets respectively. Datasets are organized into instrument-specific sub-sections and include descriptions of instrumentation, data collection methodology, and data files. Datasets that involved continuous sampling (e.g. basic meteorological data) are inventoried by date range, and site-specific datasets are inventoried in tabular format.

Section 6 provides information on other available datasets, such as navigation and science logs.

Appendix A contains the science activities log, including information on stations, positions, sampling activities, and observed weather and ice conditions (as monitored by the watch officer). Since time at a particular station can vary from hours to days, we refer the reader to Appendix B for station-specific information.

Appendix B summarizes the temporal coverage of all Met/Ocean datasets in chart-form in.

Dates are presented in international format (07 July 2010).

Times are presented are UTC (HH:MM:SS) unless otherwise noted as local standard time (LST).

Geographic positions within the dataset may be recorded in either degrees, decimal-minutes (DD°MM.MM'M'), or decimal-degrees (DD.DDDDDD°). Although decimal-degree format is highly preferred (mapping, analysis, etc), geographic positions in this report will appear as recorded in the field.

SECTION TWO: CRUISE SUMMARY

2.1 Mobilization

Mobilization of the ship commenced on 21 June 2010. The majority of instrumentation and supplies were placed and secured on the ship prior to launch from Quebec City, QC on 03 July 2010. All required equipment for the field season was loaded onto the ship at Canadian Coast Guard Depot 18, Quebec City, with the exception of the ice mass balance (IMB) buoy systems. The IMB buoys were shipped to Churchill MB as cargo and were loaded aboard during a mid-leg crew change on 21 July 2010. 24 Oceanetics ice drift beacons were also shipped to Churchill and loaded onto the ship during this crew change.

2.2 Ship Berths and Personnel

Met/Ocean data collection activities were staffed by CEOS personnel appropriate to the eight discipline-specific Met/Ocean sub-teams (Table 3).

Table 3: Met/Ocean Berth Allocations by Sub-Discipline

PRIORITY	LEG 2A	LEG 2B	LEG 3A	LEG 3B*
	POKAK	POKAK	POKAK / ICE TRANSECT	
Chief Scientist	Martin Fortier	Keith Levesque	Keith Levesque	Jean-Eric Tremblay
SEA ICE	Kerri Warner Dave Babb Ryan Galley	X 	Kerri Warner Dave Babb Ryan Galley	Matt Asplin
SYN. MET	Kerri Warner Dave Babb	Dave Babb	Matt Asplin	Matt Asplin
REM. SENS.	Kerri Warner	X	Kerri Warner	x
HEMI	Ryan Galley	X	Ryan Galley Dave Babb	x
Micromet. Tower	Emmelia Stainton Bruce Johnson	Bruce Johnson X	Kyle Swystun	Kyle Swystun Matt Asplin
Surface Buoy	Emmelia Stainton Bruce Johnson	X Bruce Johnson	X	x

*Note: Meteorological Data from leg 3B is available upon request

2.3 Crew Changes

Full crew changes occurred at the end of each 6-week period, and involved full rotation of the Canadian Coast Guard Crew and a number of science personnel. A mid-leg crew change occurred once in each leg, and were for science personnel only. During full crew changes, a Boeing 737 was chartered from Quebec City, to Inuvik for Canadian Coast Guard crew and researchers. For mid-leg crew changes, researchers traveled commercially to Inuvik or Iqaluit. Arrangements were made by ArcticNet for smaller aircraft charters to get people from Inuvik to Paulatuk for all crew changes (Table 4). Personnel were then shuttled to and from the ship via helicopter or by launch vessel.

Table 4: Summary of science rotation travel

Date	Transport to and from the CCGS Amundsen
03 July 2010	Fly commercially to Quebec City to board the ship
02 August 2010	Churchill MB; No Met/Ocean Personnel Boarded the Ship on this change
12 August 2010	ArcticNet charter between Quebec City and Inuvik, small aircraft charters between Inuvik and Paulatuk
26 August 2010	Small aircraft charters between Inuvik and Sachs Harbour. Commercial flight from Inuvik to Winnipeg
23 September 2010	ArcticNet charter between Quebec City and Inuvik, small aircraft charters between Inuvik and Paulatuk
07 October 2010	Small aircraft charters between Inuvik and Sachs Harbour. Commercial flight from Inuvik to Winnipeg
22 October 2010	Fly commercially from Iqaluit day after crew change
02 November 2010	Ship returns to Quebec City (No Met/Ocean personnel on board)

2.4 Cruise Summary by Leg

Each Leg was comprised of a series of science sampling station (hereafter referred to as ‘stations’). The duration of each station depended on the sampling regime. A set number of anticipated stations were outlined for each leg and form the basis of the sampling strategy for the 2010 cruise. Sampling operations at a given station vary by leg, research program, and environmental conditions (i.e. sea ice cover, sea state) but a general description can be found below:

- “CTD” (**C**) stations, the shortest in duration, traditionally involve one CTD (profile with the ship-mounted Rosette). The duration will depend on the depth, and by the inclusion of nutrient sampling, where bottles on the Rosette are closed at specific depths to obtain water for analysis.
- “Basic” (**B**) stations include a CTD profile plus nutrient sampling, box coring, plankton net tows, and vertical turbulence profiles, and typically require eight hours of sampling. On-ice sampling activities can be conducted if ice is present.
- “Full” (**F**) stations require anywhere between 18-24 hours and builds onto the Basic sampling activities. On-ice sampling activities can be conducted if ice is present.
- “Mooring” (**M**) stations entails a Full station plus the recovery and deployment of a mooring and possibly the Remotely Operated Vehicle (ROV).

2.4.1 Leg 1A – Transit: Quebec City to Churchill (03 July – 02 August 2010)

No partnership science activities were conducted during leg 1A. Meteorological data was collected throughout the cruise as per our group's normal ArcticNet sampling strategy and is available upon request.

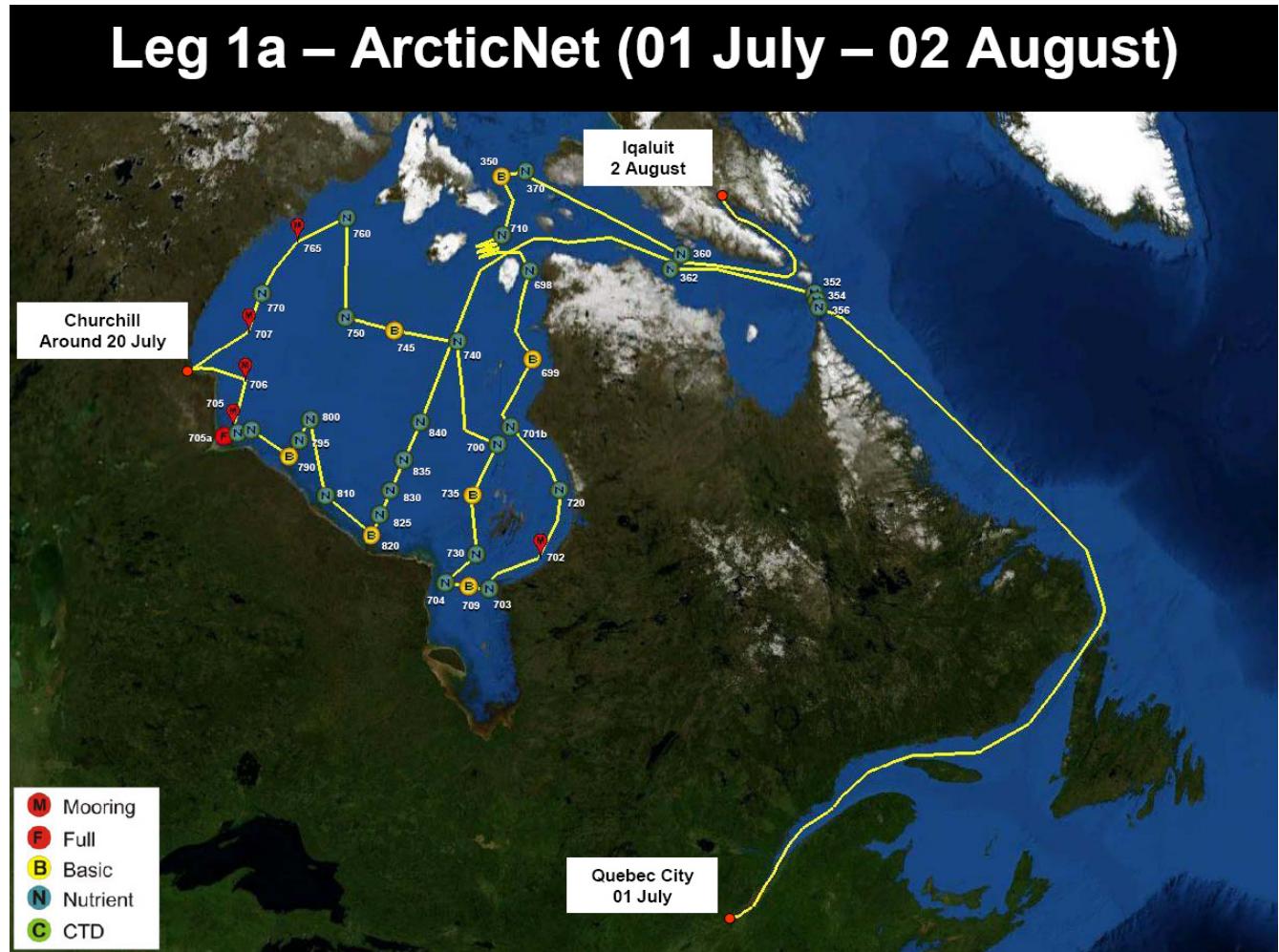


Figure 2: Leg 1A of the 2010 CCGS Amundsen Cruise.

2.4.2 Leg 1B – Churchill to Beaufort Sea (02 – 12 August 2010)

No partnership science activities were conducted during leg 1B. Meteorological data was collected throughout the cruise as per our group's normal ArcticNet sampling strategy and is available upon request.

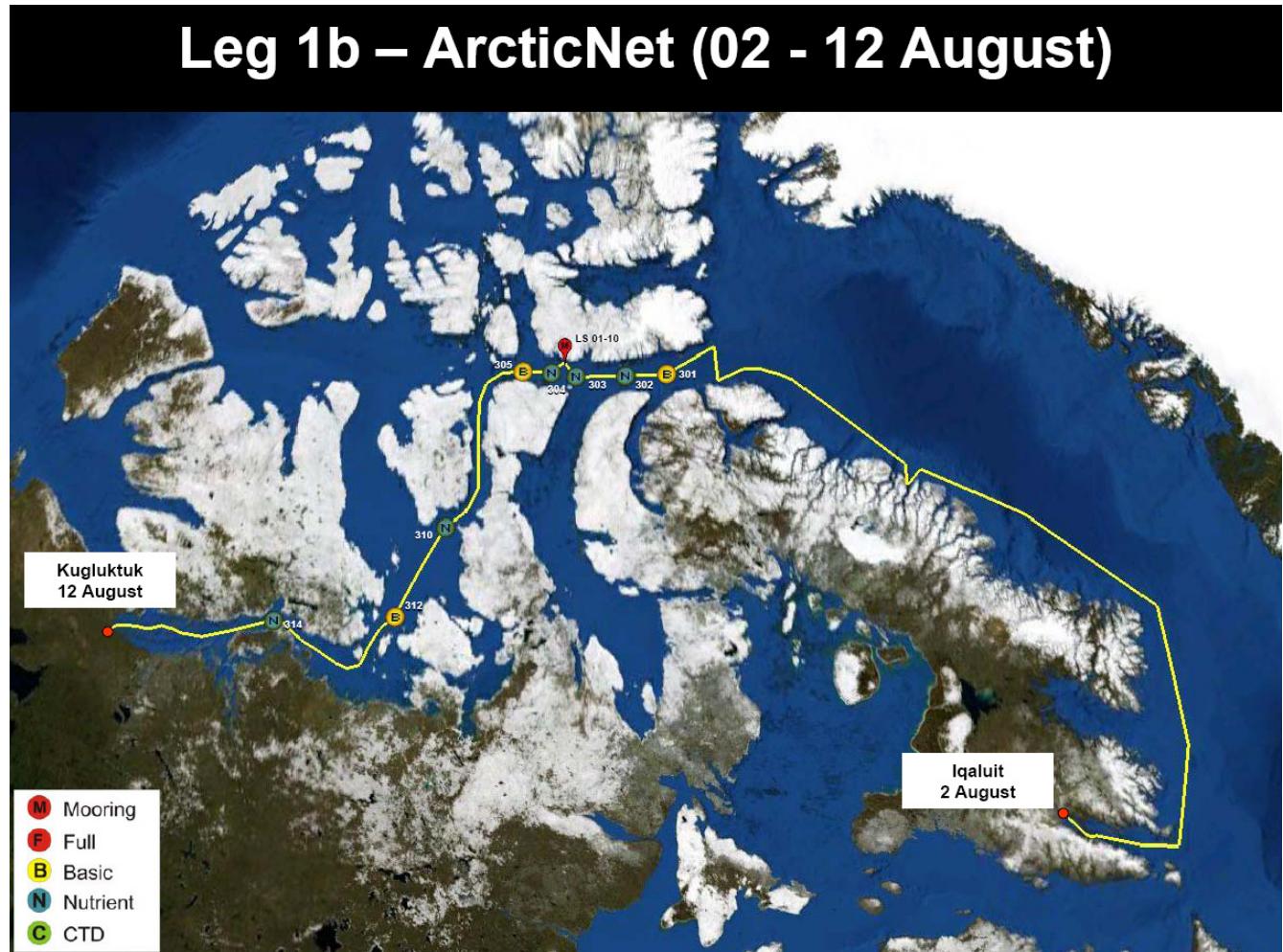


Figure 3: Leg 1B of the 2010 CCGS Amundsen Cruise.

2.4.3 Leg 2A – ArcticNet/BP Partnership (12 – 26 August 2010)

2.4.3.1 Overview of Ship Operations

Leg 2a started from Kugluktuk on 12 August (figure 4A). Between 12 August 2010 and 26 August 2010, the CCGS *Amundsen* carried out sampling operations in the EL449 and EL451 exploration acreages (BP lease blocks). ArcticNet and BP researchers sampled the planktonic and benthic ecosystems at 18 stations distributed ocean sampling activities n the BP acreages, deployed one moored surface MetOcean buoy and 12 bottom anchored Marine Autonomous Recording Units (Figure 4B). Mooring operations also included servicing and redeploying 4 subsurface moorings deployed in EL449 and EL451 in 2009. The ship sailed back to Sachs Harbour for the mid-Leg science crew change of 26 August 2010.

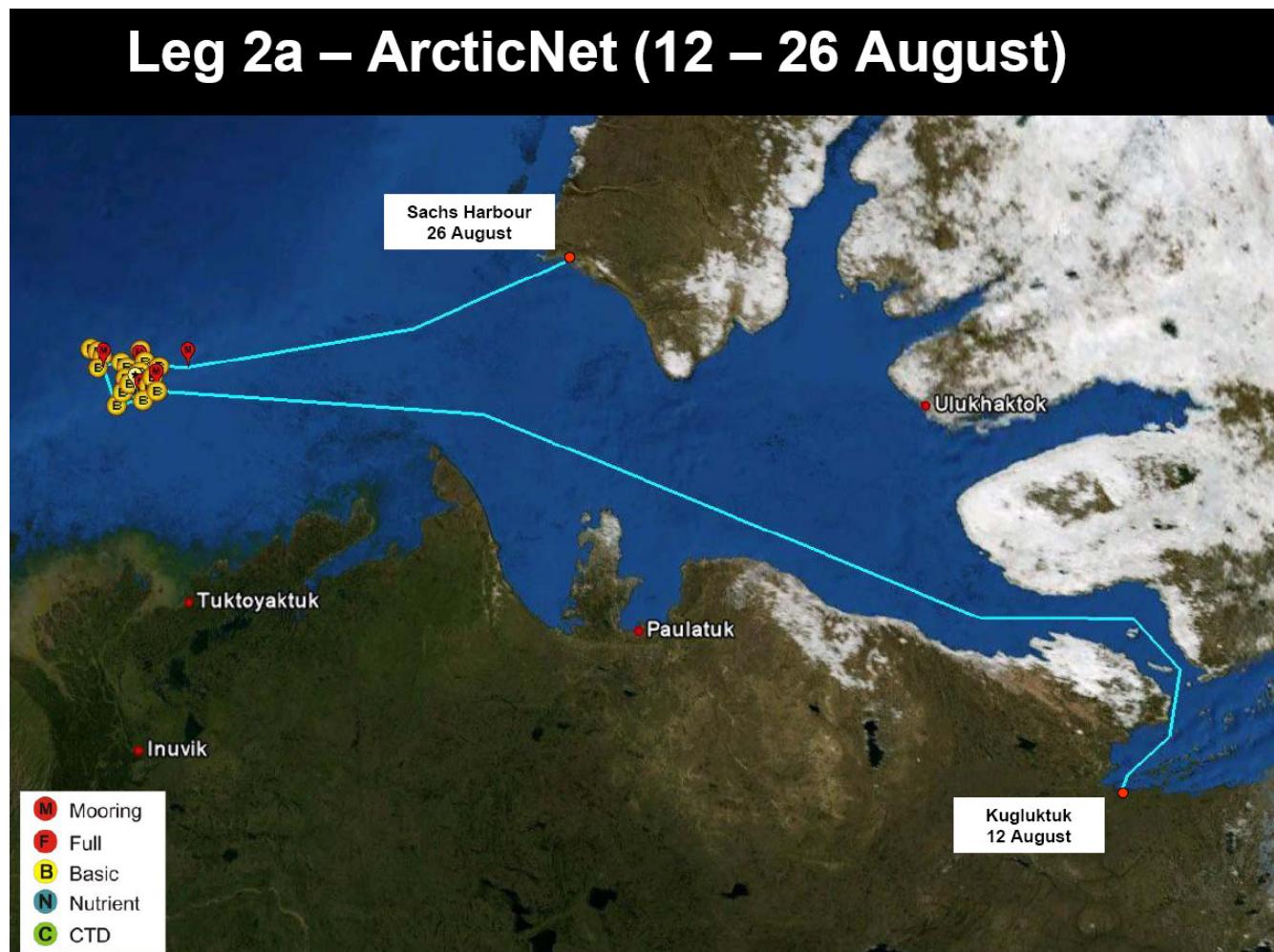


Figure 4A: Leg 2A of the 2010 CCGS Amundsen Cruise.

Leg 2a – ArcticNet (12 – 26 August)

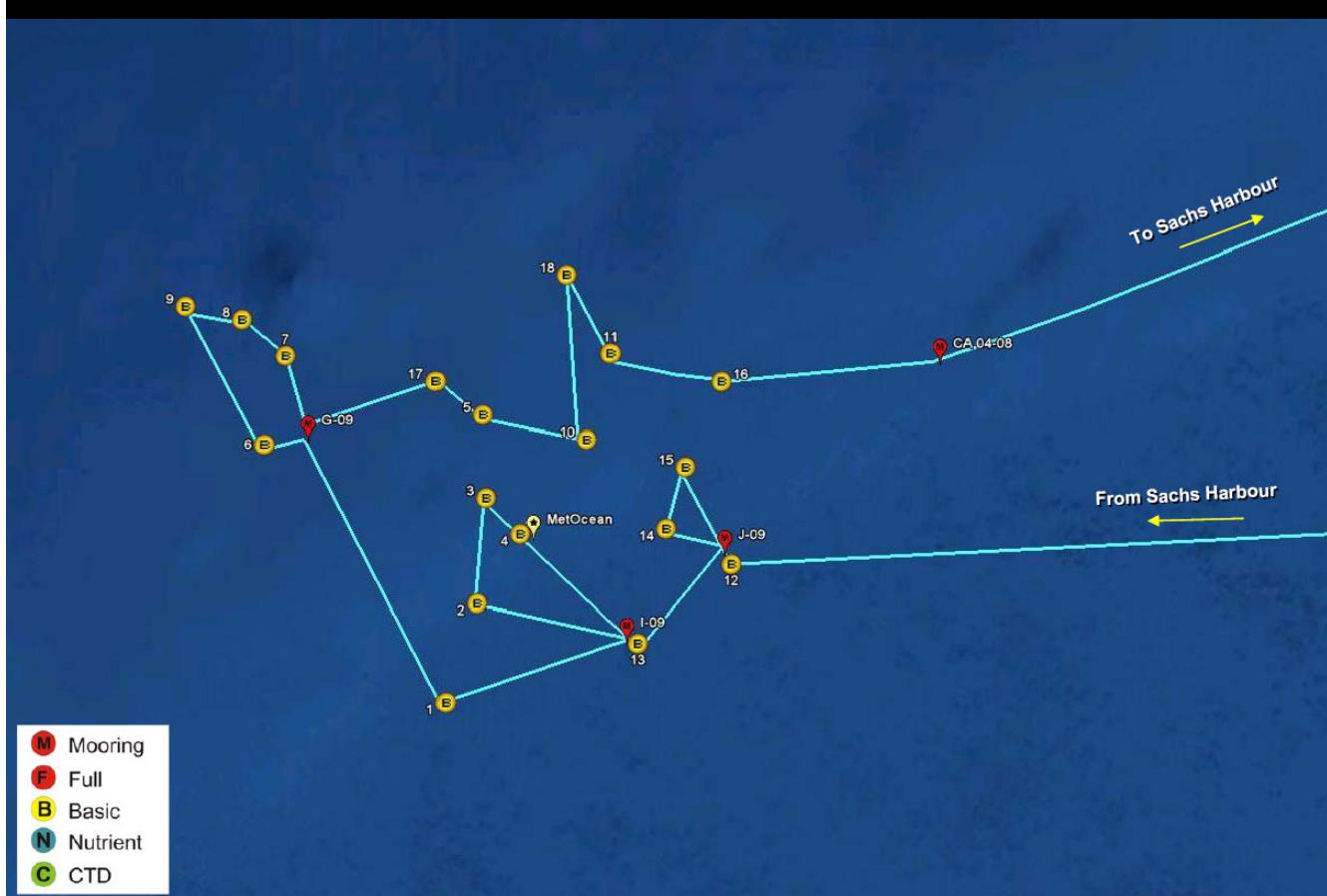


Figure 4B: Leg 2A Pokak Block science stations.

2.4.3.2 Overview of Met/Ocean Operations

HEMI surveys were conducted during Leg 2A to derive sea ice thickness and surface roughness for mobile first-year and multi-year ice. The Canadian Ice Service digital chart for the area flown for the date and location of the flights undertook this leg shows that the ice over-flown was 9+/10ths in concentration, made up of 7/10ths old ice (vast floes) and 3/10ths thick first-year sea ice (big floes)(figure 5).

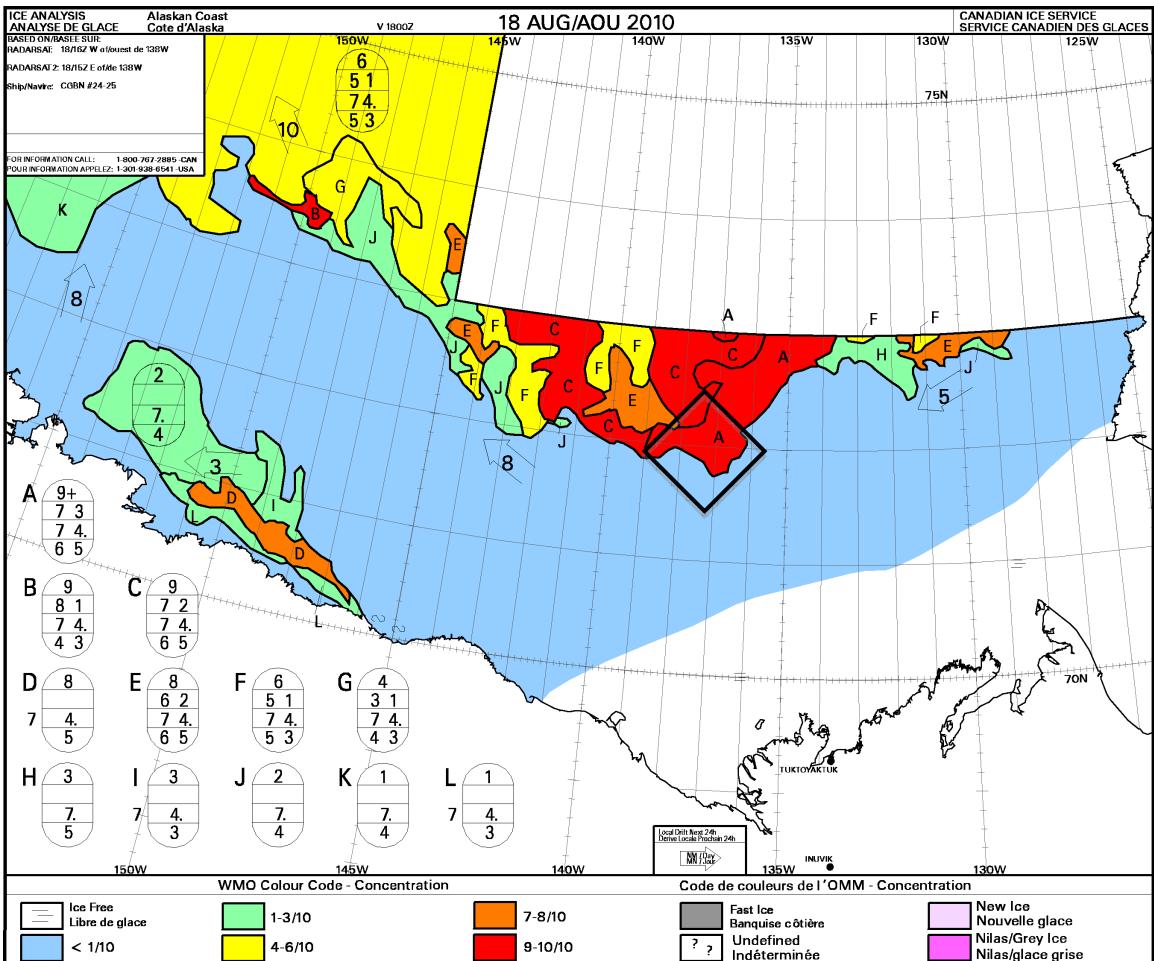


Figure 5: Canadian Ice Service digital analysis for the 'Alaska' region on 18 August 2010. The area in which we flew the IcePic is approximately denoted by the black triangle.

The system worked as it should have for two (2) flights on 18 August 2010 in the Southern Beaufort Sea centered about 72N, 137W (Figure 6). These flights were made under 'new' pilot guidelines for the BO-105 Nose Stinger Ice Probe Operations, which did not seem to affect the data quality at first glance. Three oceanetics position-only beacons were also deployed during HEMI operations on 18 August 2010. It should be noted that many meltponds were present on ice floes in the survey area (figure 6). Water at the surface sometimes creates specular reflection in the laser data making it impossible to determine the sea ice thickness at these points.

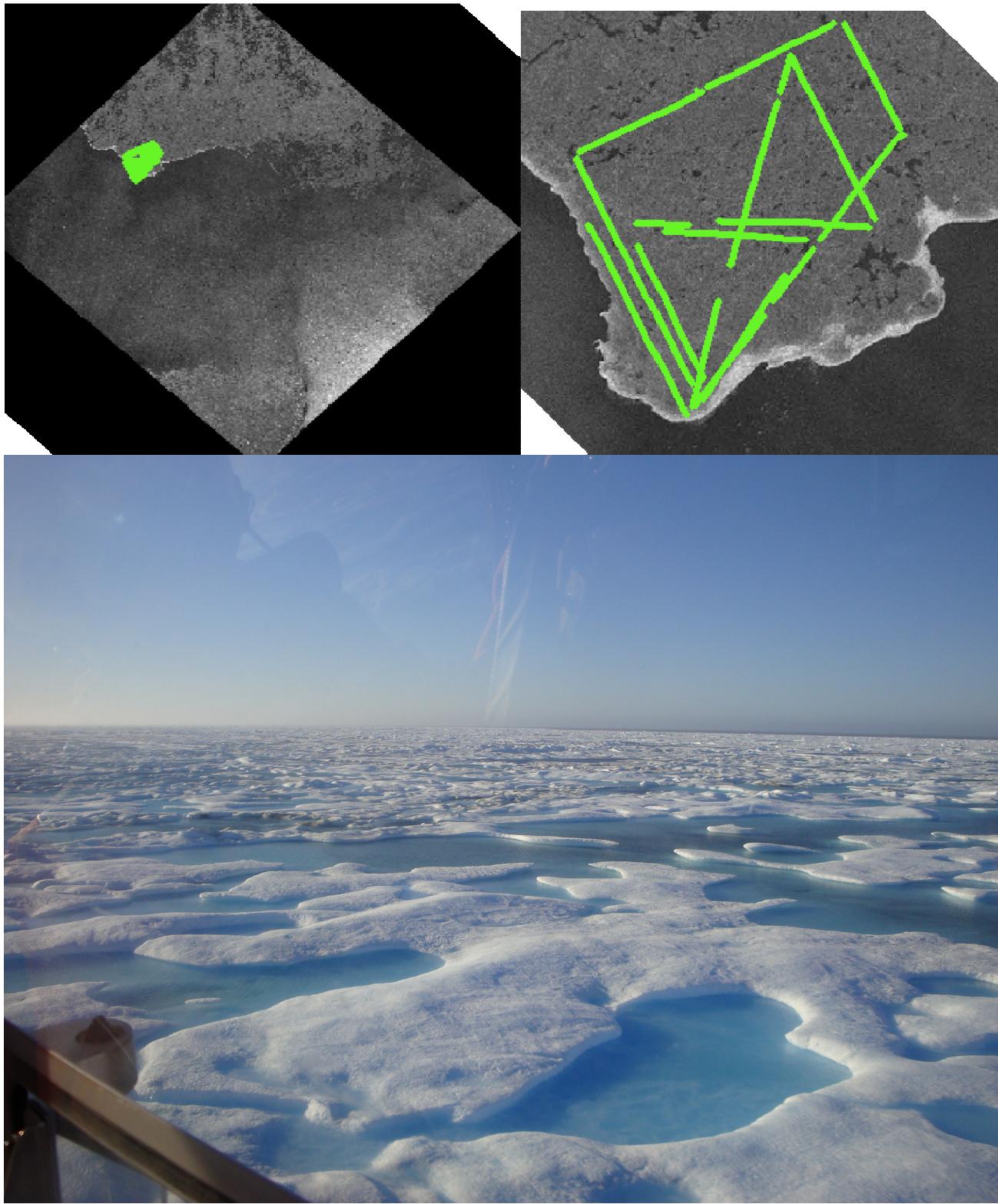


Figure 6: [Top] Radarsat-2 geotiff showing the position of the sea ice and the flight lines made on 18 Aug 2010, noting the position of Cape Bathurst in the bottom right corner (R2 Scene shows only uncalibrated DN's). [Middle] A blow-up of the top image – approximate distance from side to side is 45nm (Picture by : David Babb) [Bottom] a digital picture of the area taken from the helicopter during flight. Note the amount of water at the ice surface.

EM measurements using a C-Band Scatterometer were conducted on 18 August 2010 in order to observe the interaction of electromagnetic radiation with various ice conditions. The collected data will be used in electromagnetic modeling studies and for calibration of satellite remote sensing data. The results of this study will allow for us to improve our knowledge of the temporal evolution of sea ice physical, thermodynamic, and electrical properties during the late summer, and early ice formation season (Late August, September, October). One (1) site (71.47N, - 136.43W) was scanned using the C-Band scatterometer 18 August 2010. Coincident measurements of sea ice temperature and salinity at 5cm intervals were made.

2.4.4 Leg 2B – BP / ArcticNet (26 August - 23 September 2010)

2.4.4.1 Overview of Ship Operations

As part of the ArcticNet/BP work, Leg 2b was spent in the industry exploration acreages (EL446, EL449 & EL451) to conduct geotechnical work (piston and box coring) and a bathymetric survey (figure 7). Mooring operations were also carried out and included servicing and redeploying the 4 subsurface moorings deployed in EL 446 in 2009. The surface MetOcean buoy was retrieved at the end of Leg2b. The Vessel returned to Sachs Harbour for the full crew change of 22 - 23 September 2010.

It should be noted that the CCGS Amundsen was dispatched to a significant search and rescue operation from 27 – 30 August 2010. The ship returned to Pokak and resumed scientific sampling activities on 31 August 2010.

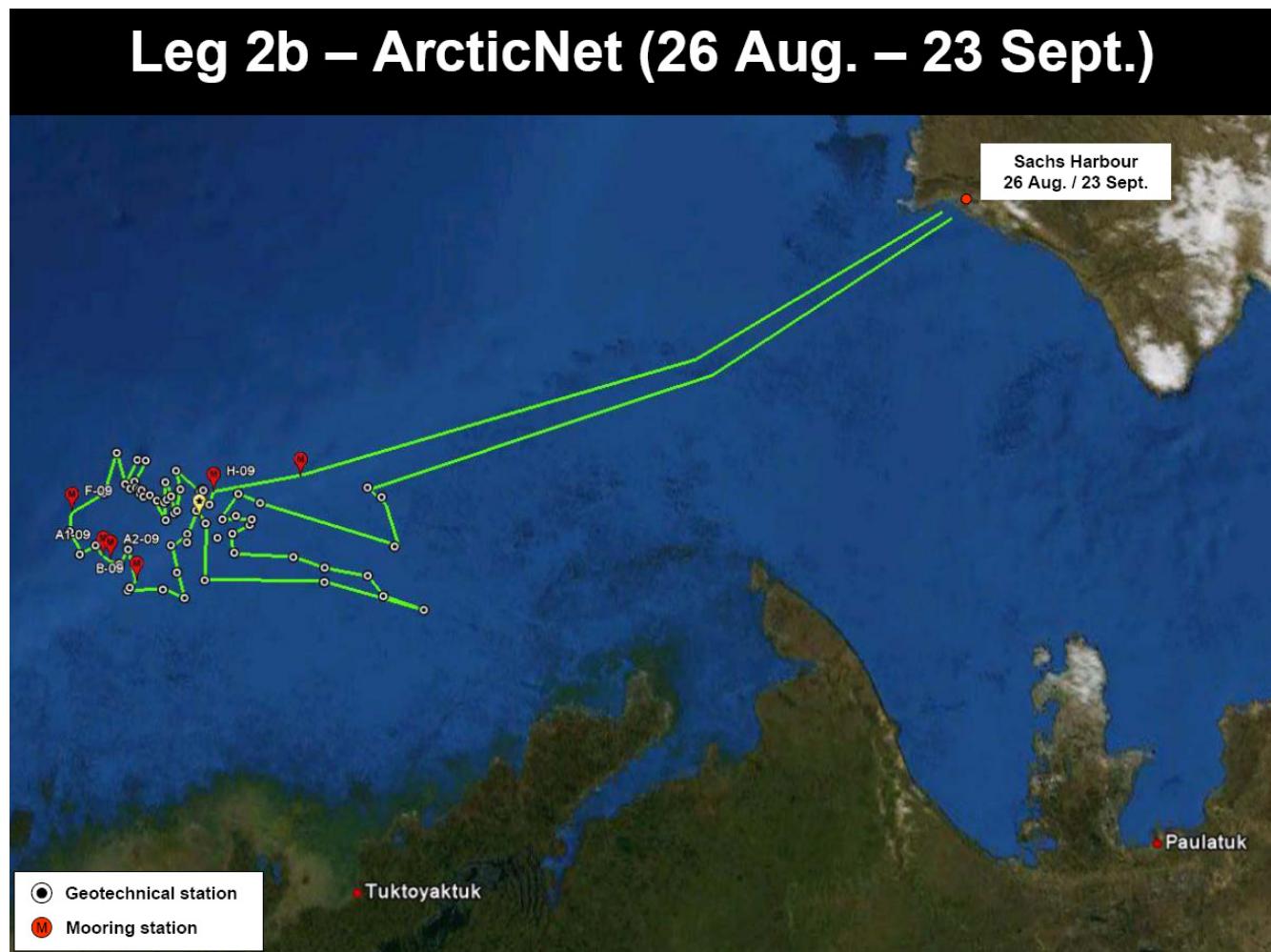


Figure 7: Leg 2B of the 2010 CCGS Amundsen Cruise.

2.4.4.2 Overview of Met/Ocean Operations

The Met/Ocean team was assigned two scientific berths for this leg. We focused on maintaining our underway meteorology, and micrometeorology (Met. tower) programs during this leg. The ship remained in the Pokak block for piston coring and bottom mapping operations. Seas were ice free at this time, and therefore no opportunities were available to collect data on sea ice.

2.4.5 Leg 3A – BP / ArcticNet (23 September – 07 October 2010)

2.4.5.1 Overview of Ship Operations

Leg 3A was a two-week sampling program that included different objectives and study areas.

The major objectives of Leg 3A were as follows:

- 1) Recover the 12 bottom-anchored marine autonomous recording units (MARU) that were deployed on 15 August 2010 in the Pokak lease block.
- 2) Recover three ArcticNet subsurface oceanographic moorings and deploy 5 new moorings in Amundsen Gulf.
- 3) Complete the bathymetric survey of priority areas in the Pokak lease block.
- 4) Conduct ice thickness and roughness surveys using the helicopter-mounted EM induction system, deploy position-only sea ice motion beacons on large ice floes, and deploy ice mass balance buoys.

Leg 3A started in Sachs Harbour on 23 September 2010 coinciding with a full Coast Guard crew change (Figure 8). Participants and crew members joined the ship using a chartered 737 jet going from Quebec City to Inuvik and then by chartered twin otter aircrafts from Inuvik to Sachs Harbour. The crew change on 23 September 2010 went long into the evening. Not all luggage and science cargo made it on board that day because diminishing daylight prevented the helicopter from completing the transfers. The *Amundsen* stayed at anchor for the night and the luggage and cargo were brought on board the next day around 9:00 AM. The *Amundsen* then departed Sachs Harbour and transited towards the first of three ArcticNet subsurface oceanographic moorings located in Amundsen Gulf. On 24 September, the three ArcticNet moorings were successfully recovered. On 25 and 26 September 2010, 11 out of the 12 MARUs deployed in the BP Pokak lease block were recovered.

Leg 3a – ArcticNet (23 Sept. – 07 Oct)

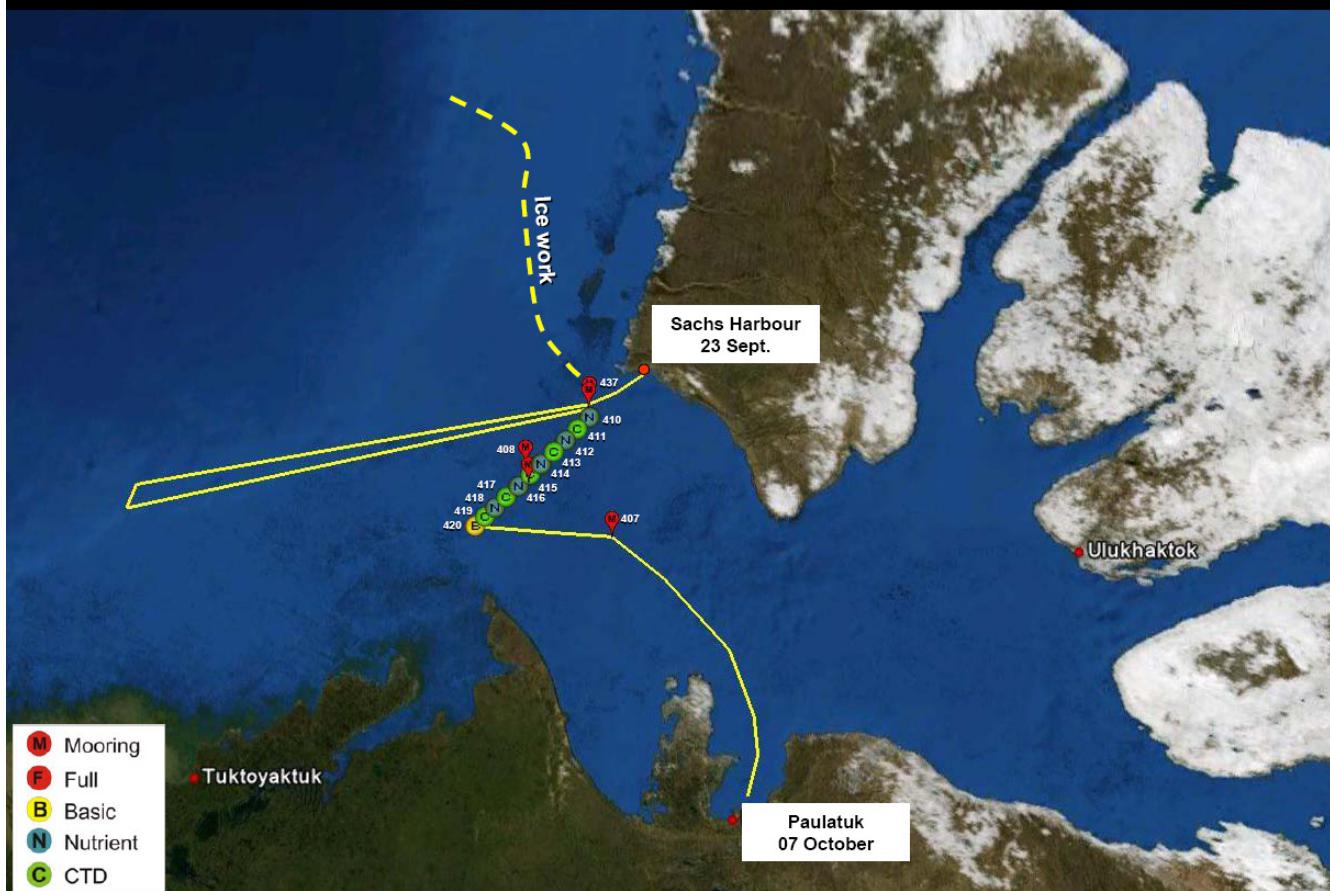


Figure 8: Leg 3A of the 2010 CCGS Amundsen Cruise.

2.4.5.2 Overview of Met/Ocean Operations

The helicopter-based EM induction system (IcePic) was used during Leg 3A to derive sea ice thickness and surface roughness for mobile first-year and multi-year ice. The system worked as it should have for two flights on 27 September 2010, three (3) flights on 28 September 2010 and one flight on 29 September 2010 in the southern Beaufort Sea centered about 74.5N, 129W. As per leg 2A flights, helicopter-based EMI flights were made under 'new' pilot guidelines for the BO-105 Nose Stinger Ice Probe Operations, which did not seem to affect the data quality at first glance. Preliminary data indicates that water at the surface sometimes creates specular reflection in the laser data making it impossible to determine the sea ice thickness at these points.

The Canadian Ice Service digital chart for the area flown for the date and location of the flights undertook this leg shows that the ice over-flown was 9+/10ths in concentration, made up of 7/10ths old ice (vast floes) and 2/10ths grey sea ice (Figure 9).

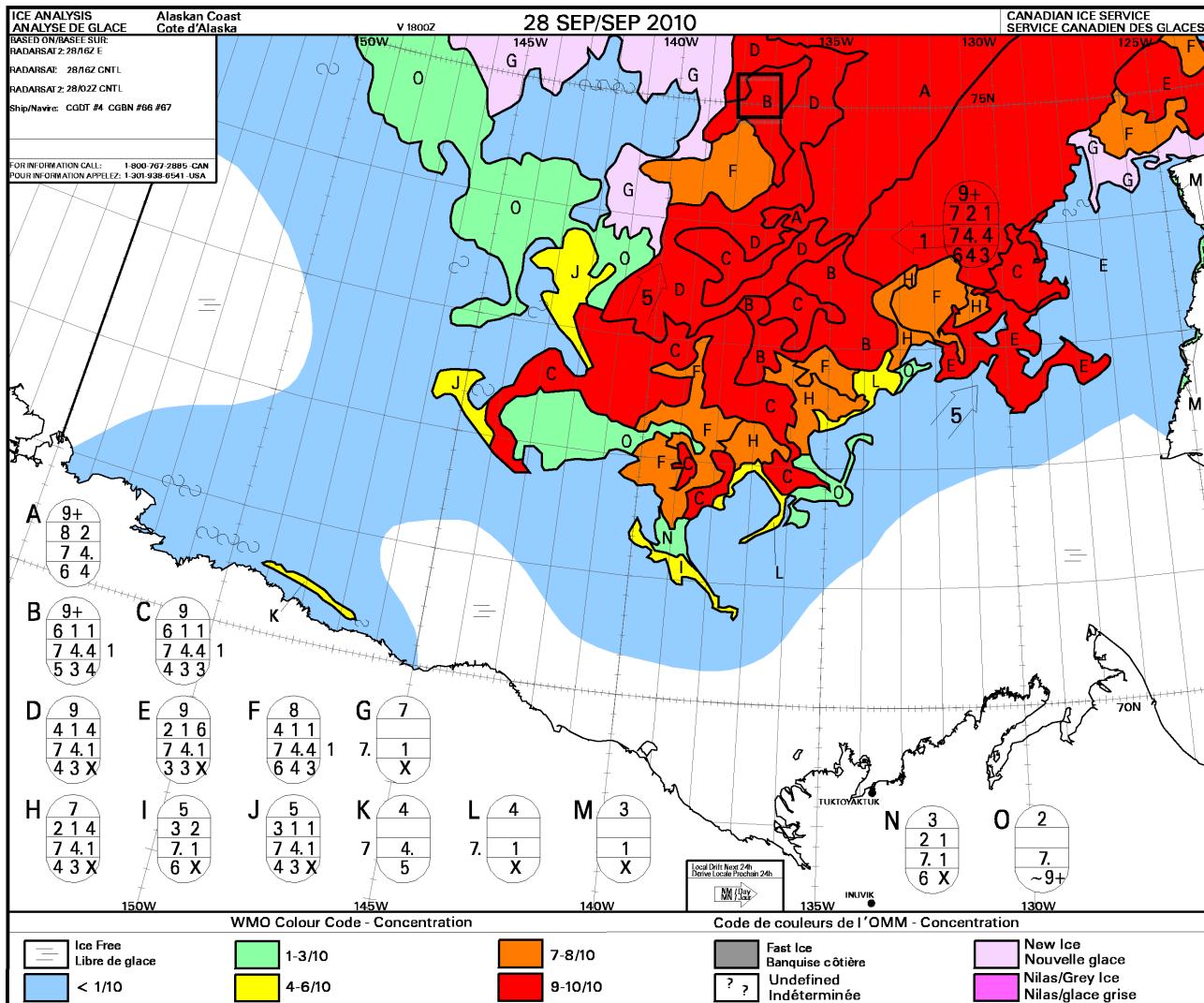


Figure 9: Canadian Ice Service digital analysis for the 'Alaska' region on 28 September 2010. The general area Amundsen operated in on 27, 28, 29 September is denoted by the black square.

Fourteen (14) Oceanetics position-only beacons were installed during operations on 27-29 September 2010. Each beacon was verified to initially be transmitting data to Winnipeg after deployment.

On 27 September 2010, a CEOS ice mass balance system (IMB04) was installed on a multi-year sea ice floe at 74°14.990N, 128°49.025W (NAD83). The ice floe was 237cm thick at the point where the temperature string was installed. There was 7cm of snow on the floe. The instrument mast, temperature string and underwater sounder were installed successfully and a successful transmission has been confirmed in Winnipeg since the system's installation.

EM measurements using a C-Band Scatterometer were conducted on various occasions between 27 September 2010 and 29 September 2010 to observe the interaction of electromagnetic radiation with various ice conditions. The collected data will be used in electromagnetic modeling studies and for calibration of satellite remote sensing data. The results of this study will allow for us to improve our knowledge of the temporal evolution of

sea ice physical, thermodynamic, and electrical properties during the late summer, and early ice formation season (Late August, September, October).

A calibration scan for the C-Band Scatterometer was conducted on 27 September 2010 at 74° 21.4751' N, 128° 27.9062' W. A total of six sites were scanned using the C-Band Scatterometer. Coincident measurements of sea ice temperature and salinity at 5cm intervals were made. Three ice cores were collected at each station for post processing in the lab to analyze density and microstructure.

2.4.6 Leg 3B – ArcticNet Western Beaufort to Iqaluit (07 – 22 October 2010)

2.4.6.1 Overview of Ship Operations

Leg 3b started on 08 October following a crew change in Sachs Harbour. No partnership met/ocean activities were planned for Leg 3B, however, meteorological data was collected throughout the cruise as per our group's normal ArcticNet sampling strategy.

cruise plan (figure 9).

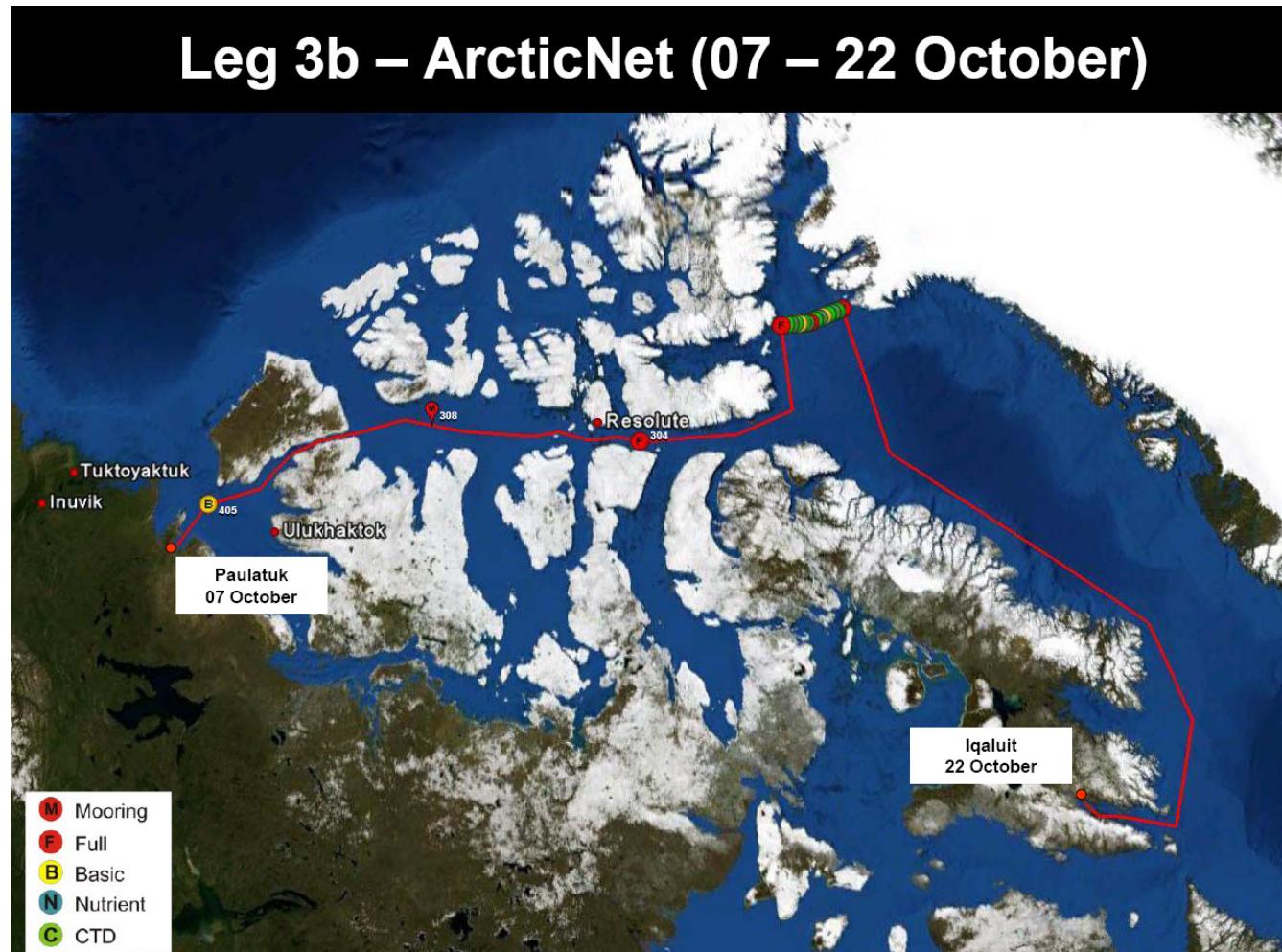


Figure 10: Leg 2b of the 2010 CCGS Amundsen Cruise.

2.4.6.2 Overview of Met/Ocean Activities

Met/Ocean activities during leg 3B were limited to ongoing maintenance of the micrometeorology tower, and boundary layer meteorology programs. All remaining Met/Ocean sampling ceased on 19 October 2010, as the ship transited along the east coast of Baffin Island towards Iqaluit.

2.4.7 Leg 3C – ArcticNet: Iqaluit to Quebec City (22 October – 02 November 2010)

With our 2010 sampling program complete, no CEOS personnel were on board for leg 3C.

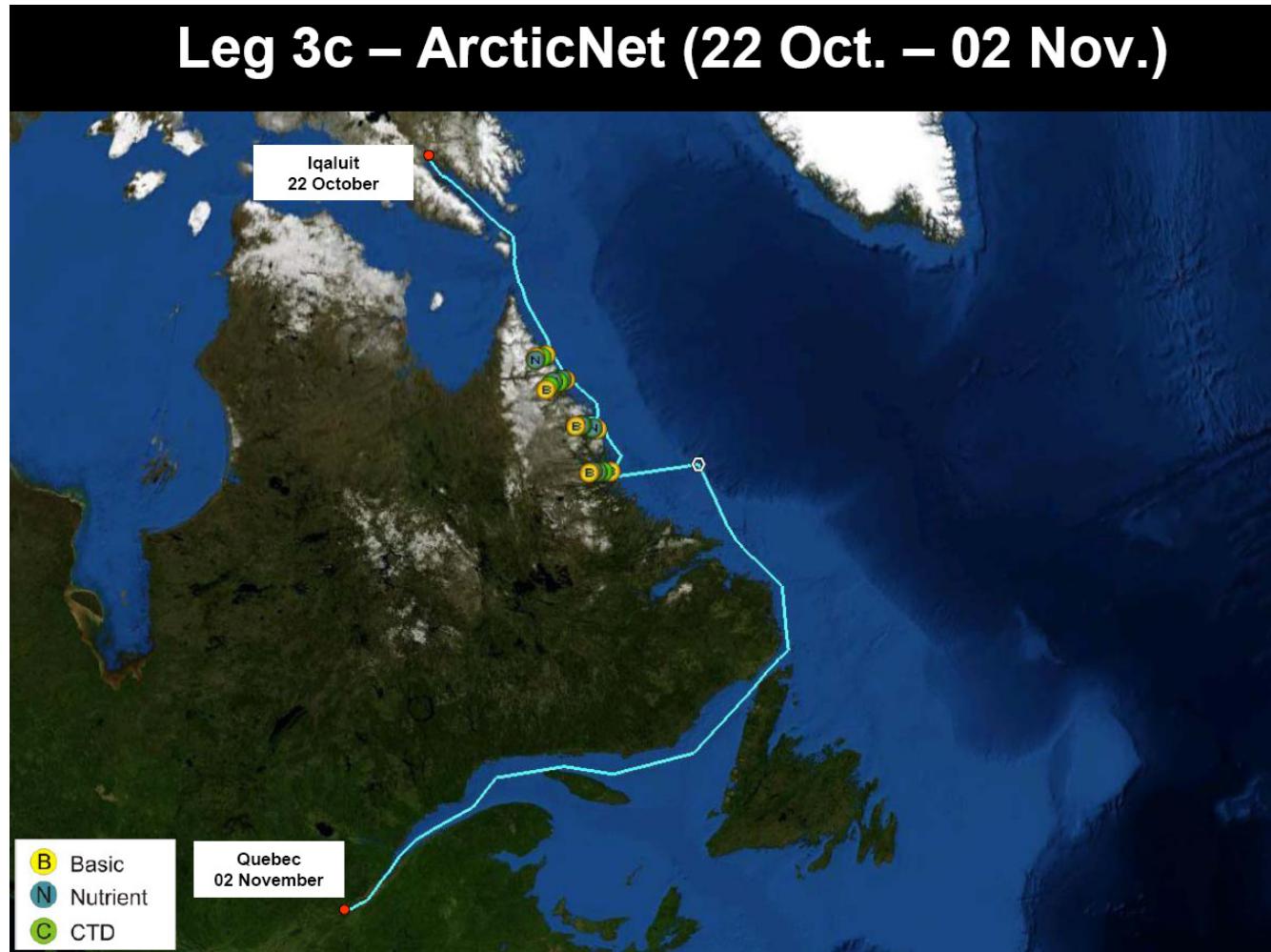


Figure 11: Leg 2b of the 2010 CCGS Amundsen Cruise.

SECTION THREE: OCEAN DATA

3.1 Mixed-Layer Buoy Program

3.1.1 Instrumentation

One buoy (hereafter termed the ‘mixed layer buoy’ or ‘MLB’) was deployed during Leg 2A to obtain data on the characteristics of the water column’s upper 45 m. The MLB suspends a 50 m string of sensors within the upper mixed layer of the water column (Figure 12). Details on the instrumentation and variables collected are provided in Table 5.



Figure 12: Mixed-Layer buoy subsurface instrumentation. [Left] JFE ALEC® compact CT sensor. [Middle] Aquadopp current profiler. [Right] JFE ALEC® PAR sensor.

Table 5: Variables and equipment associated with the Mixed-Layer and Met/Ocean Buoys.

Variable	Buoy	Sensor, Mode	Ht. to Water	Units	Specifications
near-surface current (u,v)	MLB	JFE ALEC®, model AEM-USB	-4.4, -21.4 (-4.4, -21.4)	cm/s velocity, direction	± 01 cm/s or 2% velocity ±2° direction
conductivity, temperature (CT)	MLB	JFE ALEC®, model ACT-HR Compact	-3.4,-6.4,-9.4,-12.4,-15.4,-20 30.4,-45.4 (-3.4,-6.4,-9.4,-12 15.4,-20.4,-30.4,-45.4)	mS/cm, °C	±0.05°C, ±0.05 mS/cm
light intensity (PAR)	MLB	JFE ALEC®, model MDS MkV-L	-3.4,-6.4,-9.4,-12.4,-15.4,-20 30.4,-45.4 (-3.4,-6.4,-9.4,-12 15.4,-20.4,-30.4,-45.4)	μmol/m ² /s ¹	±4% full scale
surface sea water properties: DO, pH, CTD, FL	MLB	RBR®, model XR-420CTD+DO+pH+FL	(-5.5)	% sat., pH,mS/cm °C, dBar, μg/L	±2% DO, ±0.1 pH, ±0.003 mS/cm, ±0.002°C, ±0.05% full scale, ±2%

3.1.2 Mixed-Layer Buoy Deployment

The mixed-layer buoy, suspending a 45 m string of sensors, was deployed at 250m ($70^{\circ} 56.948N$, $134^{\circ} 44.593W$), at 24:00 GMT on August 24. Eleven PAR (light intensity) sensors (JFE ALEC[®], model MDS MkV-L) and temperature/conductivity sensors (JFE ALEC[®], model ACT-HR Compact CT) were attached at 3, 6, 9, 12, 15, 20, 25, 30, 35, 40, and 45 m. Two current profiles (Nortek Aquadopp) were positioned at 3 and 45 m. The buoy was recovered on 19 September.

3.1.3 Data Summary

The mixed-layer buoy system data is stored at the following location in the database:

\OCEAN

Instrument specific data are organized into sub-folders:

...\\ADCP

...\\CT

...\\PAR

Header information is provided in the *.xls data files for each instrument in this report.

SECTION FOUR: SEA ICE DATA

4.1 Electromagnetic Induction System Sea Ice Thickness Surveys

4.1.1 Instrumentation

Sea ice thickness and surface ice roughness were measured with a helicopter-borne electromagnetic (HEMI) system, called the "IcePic", consisting of a cigar-shaped sensor package fix-mounted on the nose of a BO105 Canadian Coast Guard helicopter. The white and red "POD" fixed to the helicopter skid-gear houses the video and the second laser (Figure 13).



Figure 13: The IcePic, a fix-mounted helicopter-borne electromagnetic is shown mounted on a BO105 CCG helicopter. The red pod fixed to the helicopter skid-gear houses the video and the second laser.

The overall weight of the fixed-mount sensor package is 44 kg and consists of the laser, an EM transmitter, and an EM receiver mounted inside a cylindrical tube that is fitted to the nose of the helicopter. The EM induction system uses 4 frequencies: 1.67, 5.02, 11.7, and 35.1 KHz, to measure the distance to the ice-seawater interface. The coil separation is 1.2 m and the footprint is about 2.5 times the sensor altitude above the seawater surface. The sensor altitude above the pack-ice surface is 1.1 m when the helicopter skids are on the ice. The laser measures the distance to the ice surface. The difference between the two measurements gives the snow-plus-ice thickness.

The system can be used to "spot sample" by soft-landing and averaging the incoming 10 Hz data, or it can be used to profile floes by slowly flying at low altitude. The Ice Pic console runs on 28-volt helicopter power, and, in addition to the EM laser data, it logs GPS position and radar altimeter data derived from the helicopter's avionics. The real-time outputs are snow and ice thickness, ice conductivity, and the laser altitude.

VGPS (define) sampling was conducted following HEMI transects, following the same approximate transect line but at an altitude of ~100 m. Video images are collected with a video-laser system, which captures image frames from a downward-looking video camera in a pod mounted on the helicopter skids. Consecutive video frames can form mosaics, which are used to monitor ice conditions such as ridging, ice concentration, and floe size along the flight path. At times they capture pictures of seals along with their seal holes and occasionally polar bear tracks.

(For more detailed information on this system, and to obtain software please visit:
<http://www.geosensing.com>)

4.1.2 Data Summary

HEMI data collection flights conducted between 12 August 2010 and 07 October 2010 are summarized by flight (Table 6). The ship was positioned far from the ice edge for much of the cruise, and weather conditions were not optimal for low-altitude flight (fog, blowing snow). The majority of flights occurred from 27 – 29 September 2010 (Leg 3a), when the ship moved into areas of high ice concentration for 60 hours to conduct dedicated ice operations. It should be noted that this is far less time than was originally planned for operations in ice. As a result of this combination of factors, it was only possible to conduct EMI. There were no HEMI operators on board from 26 August – 23 September 2010 (Leg 2b) as this leg was predominantly dedicated to open-water activities within the Pokak block.

Within each of the flights, the actual locations of the HEMI and VGPS transects were dependent on the surrounding ice and weather conditions at flight time. Many of the flights consisted of a series of transects conducted over a given region 0(particularly during leg 3a). These transects are summarized in Table 6.

Table 6: HEMI data and video lines summary.

START DATE	START TIME	START LAT.	START LONG.	END DATE	END TIME	END LAT.	END LONG.
8/18/2010	14 hr 53	71.80899	-136.71107	8/18/2010	18 hr 51	71.799158	-136.7247
9/27/2010	20 hr 48	74.386997	-128.53248	9/27/2010	21 hr 07	74.26059	-128.82816
9/27/2010	23 hr 31	74.26059	-128.82816	9/27/2010	23 hr 59	74.281827	-128.67798
9/28/2010	1 hr 09	74.378678	-128.87901	9/28/2010	2 hr 27	74.436655	-129.27966
9/28/2010	15 hr 46	74.348638	-129.36614	9/28/2010	17 hr 20	74.355767	-129.18064
9/28/2010	19 hr 34	74.437977	-129.12326	9/28/2010	21 hr 15	74.519413	-128.98223
9/29/2010	1 hr 06	74.519413	-128.98223	9/29/2010	2 hr 08	74.494265	-128.7291
9/29/2010	19 hr 35	74.646245	-128.19013	9/29/2010	21 hr 23	74.752843	-127.93183

HEMI Data is stored in the database at:

\SEA ICE\HEMI\

All data has been processed into a comma-delimited text file, and is accompanied by a header and a readme file.

4.1.3 EMI Data Visualizations

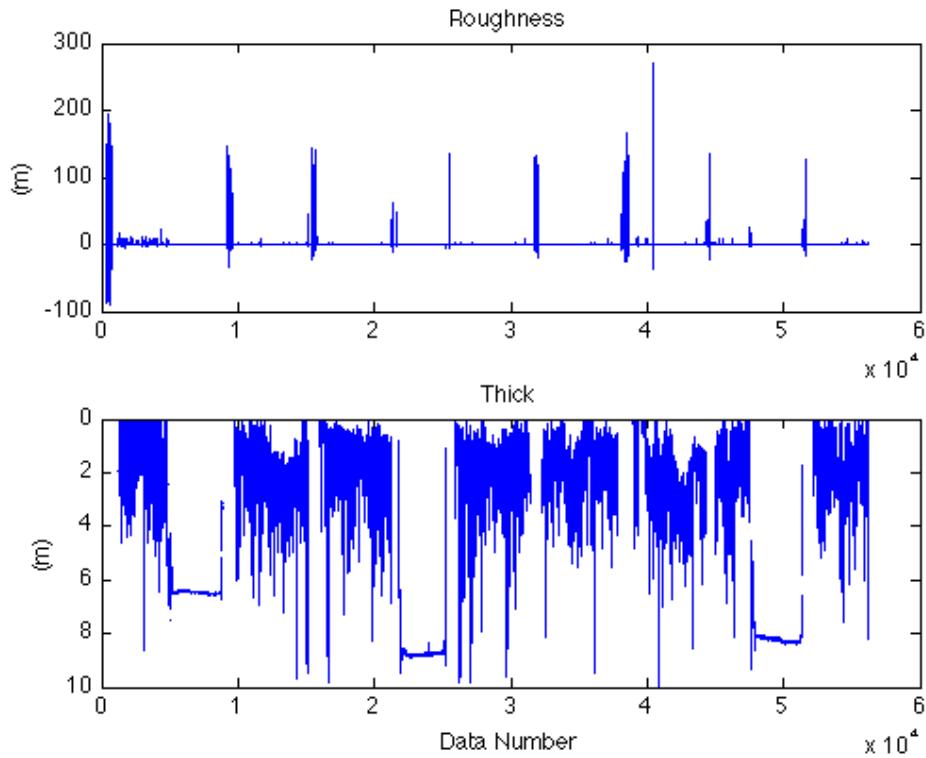


Figure 14: A sample of raw (Not quality checked, completely unfiltered) HEMI data for surface roughness (top) and ice thickness (bottom), collected during the 2010 field season.

4.2 Active Microwave Measurements (C-Band Scatterometer)

4.2.1 Instrumentation: C-Band Scatterometer

The ProSensing Inc. C-Band scatterometer is a fully polarimetric active radar system developed by ProSensing Inc (Figure 15). The transmit signal is a linear FM modulated pulse, or in other words, a chirp pulse. Its operating frequency is in C-band, with a centre frequency of 5.5 GHz and a bandwidth of 500 MHz. It is capable of measuring the full polarimetric response of the region of interest in terms of the combinations of linear polarizations: VV, HH, HV, and VH. Using proprietary software specific to the device and an internal calibration loop, it calculates the normalized radar cross section (NRCS), defined as σ_0 , which is an averaging of the radar return over the region. From a system perspective, the radar cross section is dependent upon the frequency, polarization, and angle of incidence. From a physical perspective, the radar cross section is also dependent upon the physical makeup of the target area – its electro-physical description.



Figure 15: Prosensing C-Band scatterometer

The scatterometer is used to measure the C-band microwave scattering signatures of a target region. For MY ice, open water, and landfast first year ice a swath at a series of incidence

angles will take place. The variation of measurement in the azimuthal direction is neglected as a result of the averaging in this method. Measurements from the ship require a sweep from -30° to 30° in the azimuth, with the 0° reference at a perpendicular line to the ship-side. The variation in elevation is measured with sweeps in the elevation at 5° increments on the range 20° to 60° .

4.2.2 Data Summary

The scatterometer data requires correction before it can be used. In 2009, quality assurance revealed a systematic discrepancy was detected in the processed scatterometer data. Specifically, the data is out of phase by +/- 180, independent of surface type, time of year, temperature, etc. Processed files included in the dataset are considered to be of good quality; however if further correction is required, we make any further corrected datasets available. Table 7 summarizes the scatterometer scans conducted during the 2010 cruise:

Table 7: Scatterometer scan summary

Date	Lat (N)	Long (W)	Scan Name	Processed	Notes
18-Aug	71.47	136.43	Scan-20100818-083632		no data
			Scan-20100818-083707	Yes	
			Scan-20100818-084454	Yes	
27-Sep	74.35	128.45	Scan-20100927-132257		none – CALIBRATION
			Scan-20100927-132333	Yes	
			Scan-20100927-132835	Yes	
			Scan-20100927-133338		no data
			Scan-20100927-133705		no data
			Scan-20100927-133741	Yes	
			Scan-20100927-134302	Yes	
			Scan-20100927-134822		no data
			Scan-20100927-135022		no data
			Scan-20100927-135103	Yes	
			Scan-20100927-135622	Yes	
			Scan-20100927-140142		no data
			Scan-20100927-140430		no data
			Scan-20100927-140520	Yes	
			Scan-20100927-	Yes	

			141307		
			Scan-20100927-142056		no data
			Scan-20100927-190431		no data
			Scan-20100927-190507	Yes	
			Scan-20100927-191255	Yes	
			Scan-20100927-192043		no data
			Scan-20100927-195814		no data
			Scan-20100927-195849	Yes	
			Scan-20100927-200637	Yes	
28-Sep	74.35016	129.183511	Scan-20100928-085441		no data
			Scan-20100928-085513		no data
			Scan-20100928-085519	Yes	
			Scan-20100928-090309	Yes	
			Scan-20100928-091057		no data
			Scan-20100928-104931	Yes	
			Scan-20100928-105007	Yes	
			Scan-20100928-105756	yes	
			Scan-20100928-110544		no data
			Scan-20100928-165915		no data
			Scan-20100928-165951	yes	
			Scan-20100928-170741	yes	
			Scan-20100928-171530		no data
29-Sep	74.616734	128.333576	Scan-20100929-084243		no data

		Scan-20100929-084318		no data
		Scan-20100929-085234		no data
		Scan-20100929-085310	yes	
		Scan-20100929-090126	yes	
		Scan-20100929-090914	yes	
		Scan-20100929-091703	yes	
		Scan-20100929-092451		no data
		Scan-20100929-133609		no data
		Scan-20100929-133644	yes	
		Scan-20100929-134432	yes	
		Scan-20100929-135222		no data

It should be noted that there was an ongoing date/time synchronization problem in the scatterometer central processing unit. The operators have taken care to record LST, UTC, time on laptop, and the CPU time. The filename of each scan is linked to the CPU time.

A more detailed version of Table 7 is available in the database at:

\SEA ICE\SCAT\2010_SCAT_Summary.xls

Raw scatterometer datafiles are organized by date in the database at:

\SEA ICE\SCAT\RAW

The preliminary processed ASCII scatterometer files follow the same naming convention, and are found at:

\SEA ICE\SCAT\PROCESSED

4.2.3 Data Visualizations

A comparison of scatterometer polarization data for different ice types is presented below :

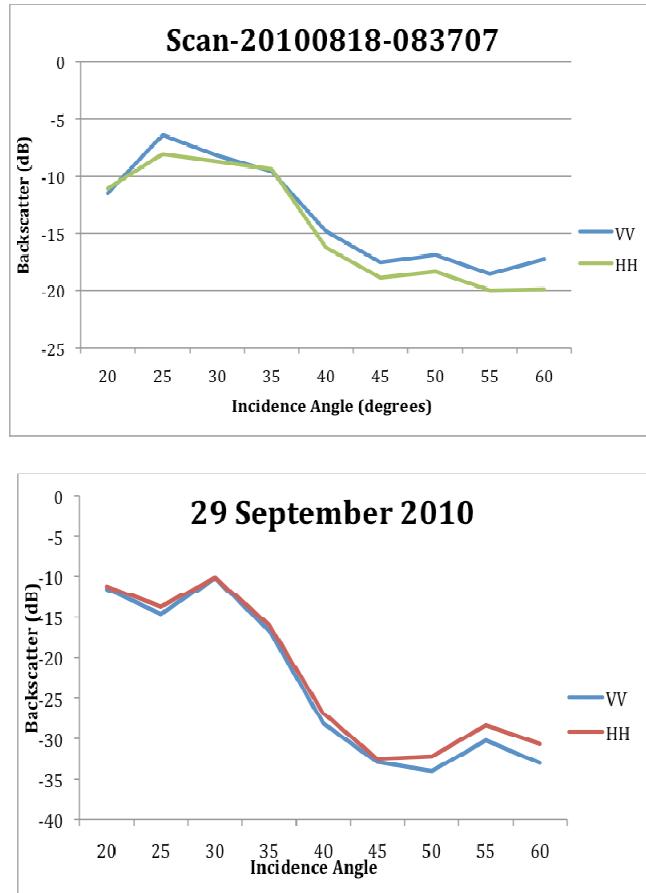


Figure 16: (Top) VV polarization and (Bottom) HH polarization comparison of FY ice collected during leg 3A

4.3 Sea Ice Physical Sampling

4.3.1 Methodology

Typical Sea ice physical sampling activities include, but are not limited to:

- Take ice cores from a location with the same snow depth close to where the snow pit is/was done (even at the same spot). Extract one core for temperature, and one for salinity.
- Freeboard (FB): determine FB from a core hole using a ruler.
- Thickness (h_i): determine h_i using an ice thickness gauge.
- Temperature (T_i): Measure at surface or snow/ice interface immediately after removing snow cover. Temperature profiles at intervals in the ice using temperature probe: immediately after extracting core, use drill to make hole to the center of ice core at a known distance from the surface, insert temperature probe to measure temperature. Shade the sensor from direct solar radiation. If T_a is colder than ice temperature, then observe maximum ice temperature. If T_a is warmer than ice temperature, then observe minimum ice temperature. Determine depth interval of temperature measurements depending on ice core thickness. Keep in mind that measuring the profile quickly is better than a high vertical resolution.
- Estimate the length of the ice core thickness (does it match the thickness gauge observation).
- Salinity: Extract an additional core. Cut it in 5 - 10 cm intervals immediately after retrieval and place in whirl-pack bags or buckets. Bring back to ship and allow to melt so that conductivity and salinity can be measured.

An ice team performing physical sampling is depicted in figure 17.



Figure 17: On-ice team taking an ice core for temperature and salinity profiles.

At each station, physical properties of sea ice in the vicinity were observed. The temperature at depth within the visited ice floe(s) was determined by coring the floe and drilling holes in it at 10 cm intervals, starting 5 cm from the ice surface. After each hole was drilled a fast-response digital temperature probe was inserted and the result recorded. The surface temperature of the ice surface was also recorded. A second core was pulled at each station and cut in the field at 10 cm intervals in order to determine the salinity profile within the ice floe (Figure 18).



Figure 18: An ice core being cut into 10cm segments for eventual salinity analysis

When it was possible for personnel to work on the ice, a no-walk zone was designated along the port side of the CCGS *Amundsen* (semi-circular area with a radius of 30m) to preserve a natural surface for the passive and active microwave measurements. On-ice physical sampling activities were conducted in close proximity to this no-walk zone. For ice thicknesses of 0 cm (e.g. grease or frazil ice) to less than 10 cm, the measurement intervals were modified to whatever was possible.

Ice cores are taken using a Kovacs Enterprises Mark II Coring system, which extracts cores with a 9cm diameter (www.kovacsicedrillingequipment.com). Ice temperature profiles (10cm interval) were measured in the field using a drill and a Hart Scientific Model 1522 temperature probe. Additional Ice cores were brought back to the ship for profile measurements (10cm interval) of salinity, by cutting about 10cm core pieces into (nearly) cubical shapes. The pieces, from which all sides that had been subject to drainage or exposed to the atmosphere were removed, were melted for measurements of conductivity using a Hach Sension5 portable conductivity meter (Hach, Loveland USA), with measurement accuracy of +/- 0.01. By measuring the temperature and salinity of the sea ice it is possible to calculate the brine volume present in the sea ice and thus get an estimate for the ice porosity. The total thickness and freeboard of the ice floe was also recorded.

4.3.2 Physical Sampling Data Summary

Physical sampling activities were generally conducted in concert with scatterometer and SBR EM scans, and were constrained by the presence / absence of sea ice. The ice edge was located 150nm north of the Pokak block, and therefore access to the sea ice was severely limited. A total of seven physical sampling excursions conducted between 12 August 2010 and 07 October 2010 (Table 8).

Table 8: Physical sampling summary of data collected, and type of ice sampled

Stn	Date (UTC)	Time (UTC)	Lat (N)	Long (W)	Ice Temp. Profile	Ice Salinity Profile	Density	Ice Thickness
N/A	08/18	1400	71.47	136.43	Y	Y	Y	FYI, 1.5m
1	09/27	2200	74 21.4751	128 27.9062	Y	Y	Y	Second year, rotten
12	09/28	1500	74 21.5753	129 11.6379	Y	Y	Y	
2	09/28	1848	74 26.2075	129 06.4522	Y	Y	Y	
3	09/28	0105	74 40.4567	128 15.0214	Y	Y	Y	
1	09/29	1648	74 37.2409	128 20.8738	Y	Y	Y	
2	09/29	2132	74 45.3497	127 56.6796	Y	Y	Y	

Physical sampling data is available in the database at:

\SEA ICE\ICEPHY\Fieldbook_2A.xlsx

\SEA ICE\ICEPHY\Fieldbook_3A.xlsx

The information contained in this file is well-described, and organized by date. Ice core profiles are recorded from the top, down (where surface = 0 cm depth).

4.3.3 Data Visualizations

Figure 19 displays the results of a sampling station on 29 September 2010. The first figure (below left) displays the temperature profile ranging from -2.3°C at the surface down to -0.96°C at the 55cm measurement. The second figure (below right) displays the salinity profile for the same floe. The top 60cm of this floe had virtually no saline content due to the fact that this sampling station was on a piece of multi-year ice (MYI). The third figure (bottom center) displays the backscattering signature from the C-Band scatterometer on the same sampling site.

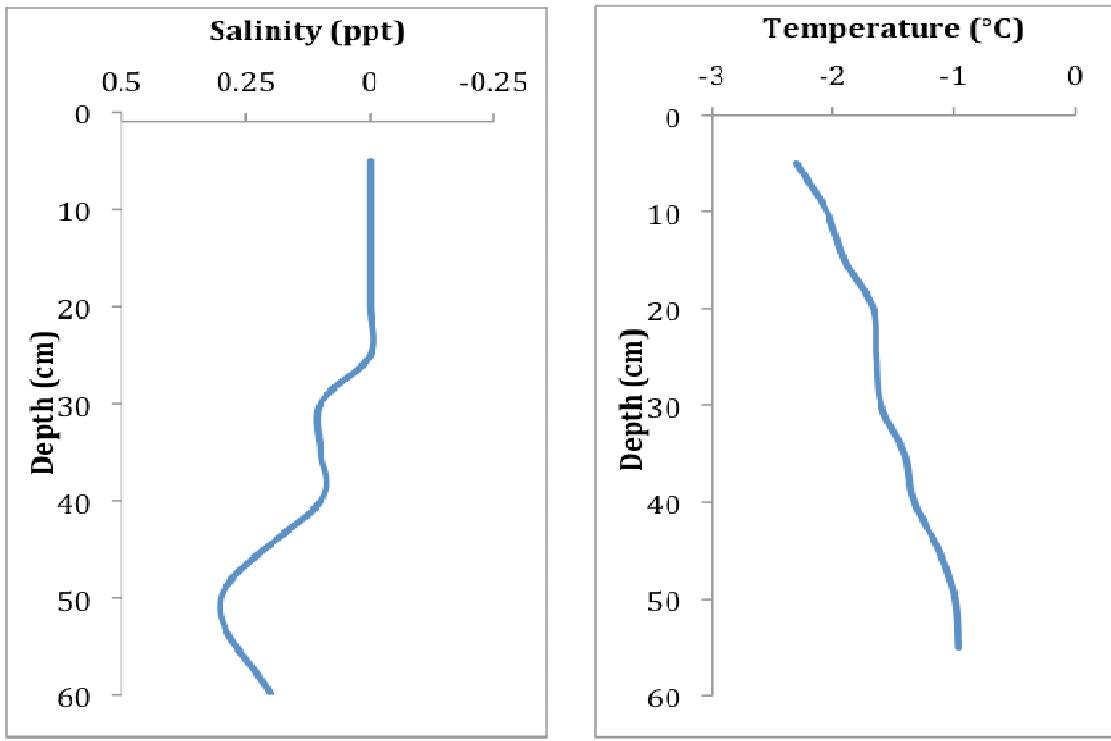


Figure 19: Salinity (top left), temperature (top right) profiles from the top 60cm of a MY ice floe sampled

The final three cores taken from each sampling station were shipped back to the University of Manitoba where they will be cut, shaved and processed in the cold lab. These samples will be used to analyze the vertical microstructure and the density of the ice at the various sites. Microstructure and density data can be made as it becomes available in the near future.

4.4 Sea Ice Mass Balance System

4.4.1 Instrumentation

The sea ice mass balance systems remotely measure physical properties of the floe in which they are installed as well as some basic meteorological variables and geographic position. The system consists of a temperature dowel containing thermistors positioned at 10 cm intervals from the top of the floe, upward- (from below) and downward- (from above) looking sonic range finders which measure the change in sea ice volume at the installation site, 2m air temperature, barometric pressure at the surface and GPS position. Each of these instruments is logged to a Campbell Scientific data logger and transmitted to a remote logging computer at CEOS in Winnipeg, MB via iridium satellite modem communication. Instrument specifications and associated variables are presented in table 9.

Table 9: Summary of sea ice mass balance system sensors.

Instrument	Variable	Accuracy
YSI 44020 thermistors (n = 45)	sea ice temperature	0.09C
YSI 44020 thermistor	2m air temperature	0.09C
CS 61202V barometer	sea level pressure	1hPa @ -50 to 60C
Benthos PSA-916 sonar altimeter	bottom thickness change	1cm (RS-232 config.)
CS SR50A sonar altimeter	surface thickness change	1cm
Garmin GPS16-HVS	Geographic position	3-5m

4.4.2 Installation procedure

The sea ice temperature dowel (2" O.D.) was installed in the sea ice using a 2" auger. The upward-looking sonic altimeter was mounted to a 2" pipe and installed below the ice on a 5.25m pipe that was installed in the ice using an 8" auger. The downward-looking sonic altimeter, GPS antenna, air temperature sensor, barometer and iridium antenna were installed on an L-shaped mast (1.75m (H) x 0.75m (W)) above the sea ice surface. Each of the three installations was made using a metal tripod base at the sea ice surface. The logging and control system as well as the batteries were housed in a watertight box at the ice surface moored by stainless steel bolts (figure 20).



Figure 20: CEOS IMB04 installed on 27 September 27 2010 in the Beaufort Sea.

On 27 September 2010, a CEOS ice mass balance system (IMB04) was installed on a multi-year sea ice floe at 74°14.990N, 128°49.025W (NAD83). The ice floe was 237cm thick at the point where the temperature string was installed. There was 7cm of snow on the floe. The instrument mast, temperature string and underwater sounder were installed successfully and data transmission is ongoing to our office in Winnipeg since the system's installation.

4.4.3 Data Summary

The sea ice mass balance buoy is presently active and regularly transmitting data. A summary of available data to date is presented in Table 10.

Table 10: Sea ice mass balance buoy data timeline (see appendix 3).

Variable	CEOS_IMB01
sea ice temperature	27 September – 08 October 2010
2m air temperature	27 September – 08 October 2010
sea level pressure	27 September – 08 October 2010
bottom thickness change	27 September – 08 October 2010
surface thickness change	27 September – 08 October 2010
Geographic position	27 September – 08 October 2010

Data is received intermittently from the buoys via iridium modem. There may be gaps or incomplete data messages in the data corresponding to periods where the iridium telemetry was not strong enough to establish, or maintain a modem link.

A sample complete IMB message is displayed below:

RING

CONNECT 9600 V42

CEOS_IMBB01

----- Parsed GPS Table -----

```
"2009-11-29 04:00:00", "$GPGGA", "040436", "7421.6761", "N", "16247.3826", "W", "1", "10", "0.8", "-13.1", "M", "0.1", "M", "", "*7C", "", "", ""
"2009-11-29 03:30:00", "$GPGGA", "033436", "7421.8419", "N", "16246.5342", "W", "1", "09", "0.8", "-3.8", "M", "0.1", "M", "", "*44", "", "", ""
"2009-11-29 03:00:00", "$GPGGA", "030436", "7422.0084", "N", "16245.6873", "W", "1", "08", "0.9", "-4.3", "M", "0.1", "M", "", "*49", "", "", ""
"2009-11-29 02:30:00", "$GPGGA", "023436", "7422.1702", "N", "16244.8256", "W", "1", "10", "0.8", "-3.5", "M", "0.1", "M", "", "*48", "", "", ""
"2009-11-29 02:00:00", "$GPGGA", "020436", "7422.3294", "N", "16243.9557", "W", "1", "10", "0.8", "-8.6", "M", "0.1", "M", "", "*4B", "", "", ""
"2009-11-29 01:30:00", "$GPGGA", "013436", "7422.4845", "N", "16243.0899", "W", "1", "10", "0.8", "-12.2", "M", "0.1", "M", "", "*73", "", "", ""
"2009-11-29 01:00:00", "$GPGGA", "010436", "7422.6377", "N", "16242.2221", "W", "1", "10", "0.9", "-16.2", "M", "0.1", "M", "", "*77", "", "", ""
"2009-11-29 00:30:00", "$GPGGA", "003436", "7422.7859", "N", "16241.3611", "W", "2", "09", "1.0", "-10.9", "M", "0.1", "M", "", "*78", "", "", ""
"2009-11-29 00:00:00", "$GPGGA", "000436", "7422.9272", "N", "16240.5153", "W", "1", "10", "0.9", "-11.5", "M", "0.1", "M", "", "*7E", "", "", ""
"2009-11-28 23:30:00", "$GPGGA", "233436", "7423.0613", "N", "16239.6929", "W", "2", "11", "0.7", "-9.9", "M", "0.1", "M", "", "*46", "", "", ""
"2009-11-28 23:00:00", "$GPGGA", "230436", "7423.1933", "N", "16238.8899", "W", "1", "10", "0.8", "-13.2", "M", "0.1", "M", "", "*71", "", "", ""
"2009-11-28 22:30:00", "$GPGGA", "223436", "7423.3240", "N", "16238.1049", "W", "1", "09", "0.9", "-10.1", "M", "0.1", "M", "", "*7B", "", "", ""
"2009-11-28 22:00:00", "$GPGGA", "220436", "7423.4520", "N", "16237.3283", "W", "1", "10", "0.8", "-20.9", "M", "0.1", "M", "", "*75", "", "", ""
"2009-11-28 21:30:00", "$GPGGA", "213436", "7423.5830", "N", "16236.5428", "W", "2", "10", "0.7", "-11.9", "M", "0.1", "M", "", "*76", "", "", ""
"2009-11-28 21:00:00", "$GPGGA", "210436", "7423.7087", "N", "16235.7767", "W", "1", "10", "0.8", "-12.0", "M", "0.1", "M", "", "*7C", "", "", ""
"2009-11-28 20:30:00", "$GPGGA", "203436", "7423.8309", "N", "16235.0374", "W", "1", "10", "0.9", "-13.7", "M", "0.1", "M", "", "*72", "", "", ""
```

----- Output1 Table -----

```
"2009-11-29 04:00:00", 2009, 11, 29, 333, 4, 0, 0, -17.3, 12.98, -18.82, 100.3, "R3.47", 3.47, 0, 0
"2009-11-29 03:30:00", 2009, 11, 29, 333, 3, 30, 0, -17.35, 12.97, -18.72, 100.3, "R3.49", 3.49, 0, 0
"2009-11-29 03:00:00", 2009, 11, 29, 333, 3, 0, 0, -17.46, 12.95, -18.61, 100.3, "R3.51", 3.51, 0, 0
"2009-11-29 02:30:00", 2009, 11, 29, 333, 2, 30, 0, -17.59, 12.94, -18.61, 100.3, "R3.48", 3.48, 0, 0
"2009-11-29 02:00:00", 2009, 11, 29, 333, 2, 0, 0, -17.83, 12.97, -18.81, 100.4, "R3.51", 3.51, 0, 0
"2009-11-29 01:30:00", 2009, 11, 29, 333, 1, 30, 0, -18.02, 12.96, -19.05, 100.4, "R3.48", 3.48, 0, 0
"2009-11-29 01:00:00", 2009, 11, 29, 333, 1, 0, 0, -18.21, 12.96, -19.05, 100.4, "R3.52", 3.52, 0, 0
"2009-11-29 00:30:00", 2009, 11, 29, 333, 0, 30, 0, -18.45, 12.95, -19.39, 100.5, "R3.48", 3.48, 0, 0
"2009-11-29 00:00:00", 2009, 11, 29, 333, 0, 0, 0, -18.7, 12.96, -19.63, 100.5, "R3.50", 3.5, 0, 0
"2009-11-28 23:30:00", 2009, 11, 28, 332, 23, 30, 0, -18.94, 12.95, -19.92, 100.5, "R3.48", 3.48, 0, 0
"2009-11-28 23:00:00", 2009, 11, 28, 332, 23, 0, 0, -19.16, 12.95, -20.12, 100.5, "R3.49", 3.49, 0, 0
"2009-11-28 22:30:00", 2009, 11, 28, 332, 22, 30, 0, -19.47, 12.94, -20.26, 100.5, "R3.50", 3.5, 0, 0
"2009-11-28 22:00:00", 2009, 11, 28, 332, 22, 0, 0, -19.83, 12.96, -20.6, 100.6, "R3.49", 3.49, 0, 0
"2009-11-28 21:30:00", 2009, 11, 28, 332, 21, 30, 0, -20.25, 12.95, -20.79, 100.6, "R3.50", 3.5, 0, 0
"2009-11-28 21:00:00", 2009, 11, 28, 332, 21, 0, 0, -20.51, 12.94, -21.13, 100.5, "R3.52", 3.52, 0, 0
"2009-11-28 20:30:00", 2009, 11, 28, 332, 20, 30, 0, -20.6, 12.94, -21.33, 100.6, "R3.47", 3.47, 0, 0
```

----- Therm Table -----

"2009-11-29 04:00:00",12.98,-13.59,-11.26,NAN,-9.7,-8.55,NAN,-7.111,-5.373,NAN,-5.174,-4.571,NAN,-3.373,-2.799,NAN,-1.578,-0.774,NAN,-1.513,-1.497,NAN,-3.297,-1.481,NAN,-1.53,-1.508,NAN,3.015,-1.486,NAN,3.997,-1.497,NAN,-1.486,-57.69,NAN,-17.61,-47.04,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 03:30:00",12.97,-13.58,-11.27,NAN,-9.69,-8.55,NAN,-7.11,-5.372,NAN,-5.167,-4.57,NAN,-3.372,-2.797,NAN,-1.577,-0.773,NAN,-1.517,-1.495,NAN,-3.29,-1.473,NAN,-1.528,-1.506,NAN,3.028,-1.484,NAN,4.004,-1.495,NAN,-1.484,-57.69,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 03:00:00",12.95,-13.63,-11.29,NAN,-9.69,-8.54,NAN,-7.096,-5.369,NAN,-5.164,-4.567,NAN,-3.369,-2.789,NAN,-1.574,-0.758,NAN,-1.508,-1.492,NAN,-3.286,-1.47,NAN,-1.525,-1.497,NAN,3.042,-1.481,NAN,4.008,-1.492,NAN,-1.481,-57.64,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 02:30:00",12.94,-13.69,-11.32,NAN,-9.69,-8.54,NAN,-7.084,-5.351,NAN,-5.163,-4.566,NAN,-3.357,-2.788,NAN,-1.573,-0.758,NAN,-1.508,-1.491,NAN,-3.286,-1.47,NAN,-1.524,-1.502,NAN,3.032,-1.48,NAN,4.009,-1.491,NAN,-1.48,-57.64,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 02:00:00",12.97,-13.75,-11.34,NAN,-9.69,-8.54,NAN,-7.084,-5.351,NAN,-5.163,-4.566,NAN,-3.357,-2.788,NAN,-1.567,-0.757,NAN,-1.507,-1.491,NAN,-3.285,-1.474,NAN,-1.523,-1.502,NAN,3.027,-1.48,NAN,4.01,-1.496,NAN,-1.48,-57.64,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 01:30:00",12.96,-13.82,-11.36,NAN,-9.68,-8.53,NAN,-7.084,-5.351,NAN,-5.163,-4.555,NAN,-3.357,-2.788,NAN,-1.567,-0.768,NAN,-1.507,-1.491,NAN,-3.285,-1.474,NAN,-1.523,-1.502,NAN,3.033,-1.48,NAN,4.004,-1.491,NAN,-1.48,-57.69,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 01:00:00",12.96,-13.95,-11.4,NAN,-9.67,-8.52,NAN,-7.084,-5.351,NAN,-5.157,-4.555,NAN,-3.357,-2.788,NAN,-1.572,-0.768,NAN,-1.507,-1.491,NAN,-3.285,-1.48,NAN,-1.523,-1.502,NAN,3.033,-1.48,NAN,4.01,-1.491,NAN,-1.48,-57.69,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-29 00:30:00",12.95,-14.05,-11.41,NAN,-9.66,-8.52,NAN,-7.078,-5.351,NAN,-5.157,-4.549,NAN,-3.357,-2.788,NAN,-1.572,-0.768,NAN,-1.513,-1.496,NAN,-3.285,-1.474,NAN,-1.523,-1.502,NAN,3.044,-1.48,NAN,4.004,-1.502,NAN,-1.48,-57.69,NAN,-17.61,-47.02,NAN,-17.41,-54.78,NAN,-17.17,-81.6,NAN
"2009-11-29 00:00:00",12.96,-14.15,-11.43,NAN,-9.66,-8.51,NAN,-7.067,-5.345,NAN,-5.151,-4.543,NAN,-3.357,-2.788,NAN,-1.572,-0.768,NAN,-1.513,-1.496,NAN,-3.285,-1.48,NAN,-1.523,-1.502,NAN,3.049,-1.48,NAN,4.01,-1.502,NAN,-1.48,-57.69,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.6,NAN
"2009-11-28 23:30:00",12.95,-14.21,-11.46,NAN,-9.64,-8.5,NAN,-7.061,-5.34,NAN,-5.14,-4.543,NAN,-3.357,-2.782,NAN,-1.578,-0.763,NAN,-1.513,-1.496,NAN,-3.285,-1.485,NAN,-1.523,-1.502,NAN,3.06,-1.485,NAN,4.004,-1.502,NAN,-1.48,-57.69,NAN,-17.61,-47.02,NAN,-17.42,-54.78,NAN,-17.17,-81.6,NAN
"2009-11-28 22:30:00",12.94,-14.45,-11.48,NAN,-9.63,-8.5,NAN,-7.06,-5.339,NAN,-5.139,-4.542,NAN,-3.355,-2.781,NAN,-1.577,-0.767,NAN,-1.511,-1.495,NAN,-3.284,-1.484,NAN,-1.522,-1.5,NAN,3.062,-1.484,NAN,4.006,-1.5,NAN,-1.479,-57.69,NAN,-17.61,-47.04,NAN,-17.42,-54.78,NAN,-17.17,-81.4,NAN
"2009-11-28 22:00:00",12.96,-14.6,-11.48,NAN,-9.61,-8.49,NAN,-7.057,-5.33,NAN,-5.136,-4.539,NAN,-3.352,-2.777,NAN,-1.567,-0.768,NAN,-1.507,-1.491,NAN,-3.28,-1.48,NAN,-1.518,-1.496,NAN,3.088,-1.486,NAN,4.01,-1.496,NAN,-1.48,-57.64,NAN,-17.61,-47.02,NAN,-17.41,-54.78,NAN,-17.16,-81.4,NAN
"2009-11-28 21:30:00",12.95,-14.71,-11.48,NAN,-9.61,-8.49,NAN,-7.056,-5.329,NAN,-5.135,-4.538,NAN,-3.351,-2.777,NAN,-1.561,-0.768,NAN,-1.507,-1.507,NAN,-3.28,-1.48,NAN,-1.518,-1.496,NAN,3.099,-1.48,NAN,4.011,-1.496,NAN,-1.48,-57.68,NAN,-17.6,-47.06,NAN,-17.41,-54.78,NAN,-17.16,-81.4,NAN
"2009-11-28 21:00:00",12.94,-14.73,-11.46,NAN,-9.61,-8.47,NAN,-7.045,-5.329,NAN,-5.135,-4.538,NAN,-3.351,-2.777,NAN,-1.561,-0.762,NAN,-1.507,-1.496,NAN,-3.285,-1.48,NAN,-1.518,-1.496,NAN,3.11,-1.485,NAN,4.011,-1.496,NAN,-1.48,-57.68,NAN,-17.6,-47.02,NAN,-17.41,-54.78,NAN,-17.16,-81.6,NAN
"2009-11-28 20:30:00",12.94,-14.75,-11.44,NAN,-9.61,-8.47,NAN,-7.045,-5.329,NAN,-5.13,-4.527,NAN,-3.351,-2.771,NAN,-1.572,-0.768,NAN,-1.507,-1.496,NAN,-3.28,-1.48,NAN,-1.518,-1.496,NAN,3.137,-1.48,NAN,4.011,-1.496,NAN,-1.48,-57.68,NAN,-17.59,-47.04,NAN,-17.41,-54.81,NAN,-17.16,-81.6,NAN

END TRANSMIT

+++

NO CARRIER

The data has been cleaned and organized into a single excel file:

\SEA\ICE\IMB\IMBB_04_2010.xls

The IMB dataset provides sea level pressure, air temperature, bottom thickness change, and surface thickness change. A header summary is presented in Table 11.

Table 11: Header information

Header	Description
Date - Time	Date – time (excel)
\$GPGGA	GGA NMEA Message
LAT	Latitude
N/S	North / South Latitude Flag
Lon	longitude
E/W	East / West Longitude flag
yy	GPS Year
mm	GPS Month
dd	GPS Day
doy	Day-of-year
hh	GPS Time: Hours
mn	GPS Time: Minutes
ss	GPS Time: Seconds
T-logger	Data logger temperature
Signal_quality	Data Logger Signal quality
Voltage	Data logger battery voltage
T-air	Air temperature
Atm pr (kpa)	Barometric pressure
Raw – UW	String (underwater sonar)
UW	Underwater sonar
Raw-SR50	Raw Snow sounder raw distance (m)
Quality	Snow sounder signal quality
SR-50	Snow sounder raw distance (m)
Therm_1...38	Thermister Chain

The ‘Therm1 to 38 provides half-hourly 10 cm resolution sea ice temperature profile data (°C). Values where data is not available are marked with NAN (not a number).

4.5 Ice Motion

4.5.1 Instrumentation

Ice motion data was recorded from the Oceanetic (1989) model 703 Iridium Ice tracking beacons, or ‘ice drift beacons’ (Figure 21), which are 20 cm in diameter and 54 cm in height, with a weight of 11.6 kg.



Figure 21: An Oceanetics model 703 Iridium Ice tracking buoy. The number on the front corresponds to the last five (sometimes six) digits of the iridium model ID.

Beacon life expectancy is on the order of 10 months for continuous operation, although the measurement duration is typically less as the beacons will sink if the ice floe they are installed upon melts or breaks up. Ice motion buoys are deployed using an ice auger to drill a hole that is approximately 25cm in depth. GPS positions and time and date stamps are reported and transmitted through a Short Burst Data (SBD) packet to the Iridium modem system by email. Buoys are equipped with Light Emitting Diode (LED) indicators to determine modem status, and each modem is uniquely identified using an International Mobile Equipment Identity. Software called SatTerm is provided so that commands may be sent to the modem, while data is collected via an email account that receives SBD messages from the modem using a “Server for Trackers” application. The resulting data format is user-defined and

selected from a variety of formatting options. In this instance, ice motion data is in comma-delimited text format and includes beacon identification, date, time and position, namely latitudinal and longitudinal coordinates.

Ice drift beacons are deployed manually on MY ice (preferred), or thick FY ice floes (figure 47). The Deployment location is usually selected based upon local ice conditions. Anywhere from one to three ice beacons may be deployed at once. The ice beacons are normally taken via helicopter to a suitable ice floe where a 9" auger hole is drilled to a depth of approximately 20cm. The ice beacons are then placed in the hole and packed with snow, and activated by removing a magnet on the side of the buoy. The deployment time, location, ice type, and buoy ID are recorded and monitored. The beacon data is transmitted via Iridium satellite modem every two hours in encoded messages, which are then translated and processed at the University of Manitoba. Ice velocities and trajectories can then be calculated from this data.



Figure 22: Ice beacon deployment. A site is selected with good line-of-sight to the horizon, and an 8" 20-cm deep hole is drilled using a gas-powered auger. The beacon is installed upright, and activated.

4.5.2 Data Summary

14 ice drift beacons were deployed on mobile FY or MY ice during the 2010 field season. Where possible, a triangular deployment plan was implemented so that drift beacon tracks could be compared to identify ice shear and local ice vorticity. Of the 17 ice beacons deployed, 12 of these beacons were deployed in 4 such triangular configurations. Ice beacon deployments are summarized in Table 12.

Table 12: Beacons deployment summary :

Serial Number	Date Deployed	Latitude	Longitude
289110	2010 08 18	72°N 52.499	137°W 05.054
285100	2010 08 18	72°N 07.458	137°W 24.673
284100	2010 08 18	71°N 57.506	136°W 42.249
25480	2010 09 28	74°N 37.750	129°W 12.202
96630	2010 09 28	74°N 45.621	129°W 17.889
23490	2010 09 28	74°N 42.637	128°W 49.458
27340	2010 09 28	74°N 27.328	128°W 21.573
22370	2010 09 28	74°N 21.025	129°W 09.127
24350	2010 09 28	74°N 29.664	128°W 44.408
21490	2010 09 29	74°N 44.230	127°W 54.229
21350	2010 09 29	74°N 50.572	127°W 38.244
27480	2010 09 29	75°N 01.491	127°W 02.534
20350	2010 09 29	74°N 50.105	128°W 14.388
23340	2010 09 29	74°N 43.068	128°W 03.940
29340	2010 09 29	74°N 43.981	127°W 46.057
27350	2010 09 29	74°N 33.195	128°W 08.174
28330	2010 09 29	74°N 35.697	129°W 16.227

The datum for the above-mentioned positions was NAD83.

Drift buoy data collection has ended, and all available data from the 2010 field season is available in the dataset at:

\SEAICE\IDB\IDB_2010.XLS

Data file header description is as follows:

Iridium modem ID
Date: (dd/mm/yyyy)
Month
Day
Year
Hour
Minute
Seconds
AM/PM
Latitude (decimal degrees)
Hemisphere (N/S)

Longitude (decimal degrees)

Hemisphere (E/W)

Speed (m/s).

direction (degrees).

It should be noted that ice beacon deployment lifespans were considerably shorter than in previous field seasons. We attribute this outcome to several operational and environmental factors that were beyond our control. For further information, please review the report on ice beacon deployment lifespans, which is found at:

\\SEAICE\\IDB\\sea_ice_tracking_beacon_longevity_report.pdf

4.6 Surface Temperature

4.6.1 Instrumentation: Infrared Transducer

A downward-looking Infrared temperature sensor (Model Everest 4000.4ZL), mounted at 30° from the vertical, took surface temperature measurements at a 15 second sampling interval. The instrument is installed on the starboard gunwale on the foredeck, facing the ocean surface (Figure 23). It operates at 8 - 12 microns wavelength of the electromagnetic spectrum. The data collected from this instrument is typically used to characterize the surface temperature during C-Band scatterometer scans.



Figure 23: Everest 4000.4ZL mounted on the starboard gunwale of the CCGS Amundsen at 30° from the vertical.

The infrared transducer was deployed during 2010 as part of the micrometeorological tower and data is available in the daily processed MET files.

\ATMOS\TOWER\MET\

4.7 Ice Thickness Images

4.7.1 Instrumentation

A downward-looking AXYS NETCAM camera monitored ice thickness where ice breaking was necessary. The camera was mounted on the port side of the ship, at a height of ~8m above the sea (Figure 24). When breaking through ice, some of the broken ice floes will turn on their side. Estimates of ice thickness can be processed from this imagery, and geoencoded using the time stamps. It should be noted that this technique of monitoring sea ice thickness performs poorly during the summer months, as heavily-decayed, thick old ice floes tend to be pushed away from the ship, rather than turn on their side. Some of the images are also useful for determining stage of ice development.

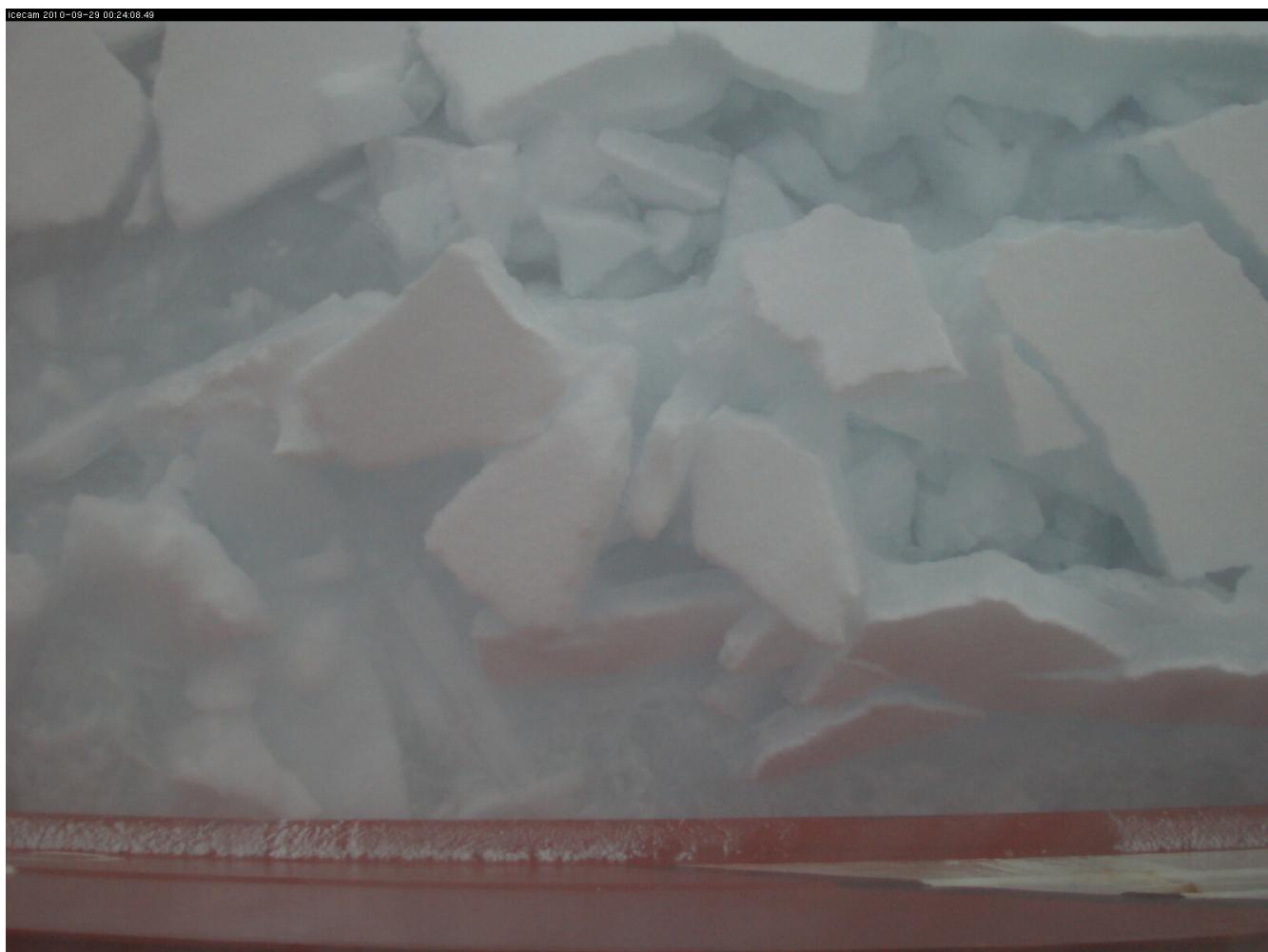


Figure 24 : Sample IceCam image from 29 September 2010.

4.7.2 Data Summary

Ice thickness camera images were collected during the following dates:

27 September 2010
28 September 2010
29 September 2010
30 September 2010
09 October 2010
10 October 2010
11 October 2010
12 October 2010
13 October 2010
15 October 2010

The images are available in the database at:

\SEA ICE\ICECAM\YYYY-MM-DD\

4.7.3 Data Visualizations

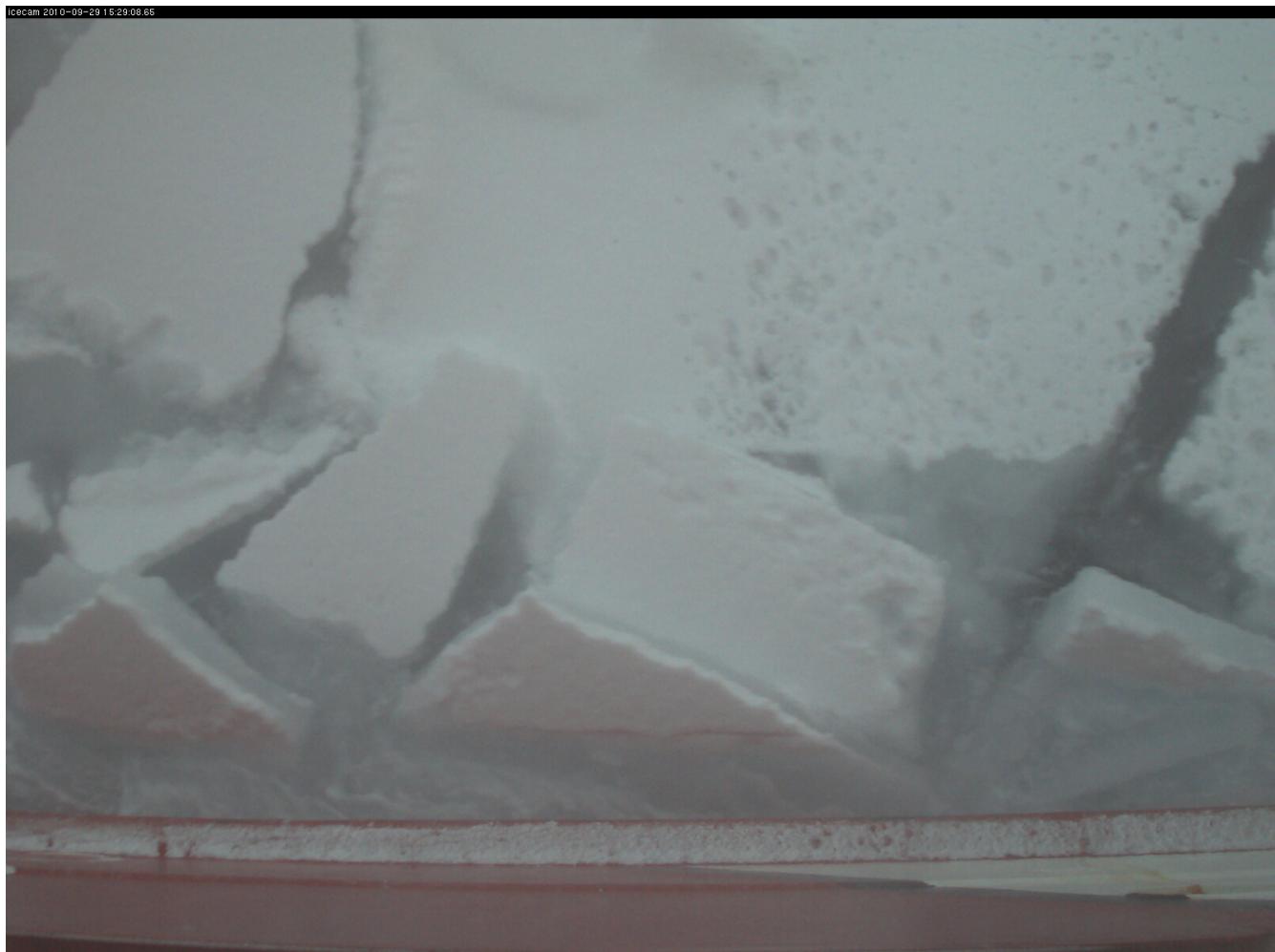


Figure 25: Sample ice thickness photo

SECTION 5: METEOROLOGICAL DATA

5.1 Micrometeorology Tower Program

5.1.1 Introduction

The motivation for this work stems from the general poor understanding of the processes that exchange nutrients, heat and momentum between the near ocean surface and atmosphere in the Arctic Ocean and peripheral seas. The group's focus is the exchange of CO₂, heat and momentum, and in particular to achieve a better understanding of the role of sea ice (full and partial ice cover) and surface surfactants on the transport and exchange of the respective entities.

Specific objectives relate to the development of tools (observation, model, and remote sensing) to assist with regional budgeting of (primarily) heat, CO₂, and momentum, and in the longer term, to develop the necessary process-level understanding of the exchange processes, to forecast how the ocean's response to climate change and variability will affect the atmosphere-ocean cycling of CO₂.

The surface meteorology and flux program of the CCGS *Amundsen* is designed to record basic meteorological and surface conditions, and to study exchanges of momentum, heat and mass across the atmosphere-sea ice-ocean interface in support of the objectives described above.

Novel to our air-sea studies is the ship-based application of the eddy covariance technique for the direct measurement of heat, CO₂ and momentum. Eddy covariance represents the lone local scale (100s m to km) direct micrometeorological measurement of the respective fluxes.

Our group's 2010 ArcticNet monitoring and sampling program was expanded to accommodate the monitoring requirement of BP within the Pokak block of the southern Beaufort Sea. The emphasis of the expanded program is on site specific time-series monitoring of near surface meteorology, surface wave parameters and near surface water currents, and upper ocean light, temperature and current profiles using moored buoys.

5.1.2 Methods

The micrometeorological tower located on the front deck of the CCGS *Amundsen* (Figure 26) provides continuous monitoring of meteorological variables and eddy covariance parameters. The tower consists of slow response sensors that record bulk meteorological conditions (air temperature, humidity, wind speed/direction, surface temperature) and fast response sensors that record the eddy covariance parameters ($\text{CO}_2/\text{H}_2\text{O}$ concentration, 3D wind velocity, 3D ship motion, air temperature) (Table 13). In addition, radiation sensors (Figure 27, Table 13) were installed on the roof of the wheelhouse to provide information on incoming long-wave, short-wave, ultraviolet, and photosynthetically active radiation. All data was logged to Campbell Scientific dataloggers; a model CR3000 logger was used for the eddy covariance data, a CR1000 logger for the slow response met data, and a CR23X for the radiation data. All loggers were synchronized to UTC time using the ship's GPS system as a reference. Ship heading and location (lat., lon.) were measured to compensate measured apparent wind information for ship direction and motion.

The eddy covariance system on the tower makes use of two separate gas analyzers and a single 3D sonic anemometer. The dual gas analyzers system allows us to make use of both closed path and open path eddy covariance systems. The open path gas analyzer has the benefit of making measurements concurrently with the sonic anemometer, but the closed path gas analyzer is not as easily disturbed by adverse weather conditions.

In order to make sure that the two systems are comparable, careful calibrations are performed on both instruments. The closed path system is based on a LI-7000 gas analyzer which employs two optical cells, one of which was used to monitor the drift of the instrument by constantly passing a stream of ultra-high purity N_2 . In addition, the sample cell of the instrument is calibrated daily using the ultra-high purity N_2 to zero the CO_2 and H_2O measurements, and a reference gas of known CO_2 to span the instrument. Occasionally, a span calibration of the H_2O sensor is performed using a dew point generator (model LI-610). The open path gas analyzer (LI-7500) cannot be calibrated as conveniently, and so it is calibrated approximately every three weeks. In general, we find that this is effective for this particular instrument, which does not drift significantly over time.

The ship motion correction necessary for the application of the eddy covariance technique requires accurate measurement of ship motion (3-axis measurement of angular acceleration and rate), heading and location. Rotational motion is monitored using a multi-axis inertial sensing system. Data related to heading and location is available from the ship's GPS and gyro. Using these data yaw, pitch and roll, in addition to translational motion is calculated, and collectively this information is used to correct our 3D wind measurements.

In addition to the eddy covariance solution to air-sea fluxes, data are collected for the more commonly used bulk approximation. Note however that the bulk approximation is unable to deal with ice in the flux footprint. This last point is a central research theme.

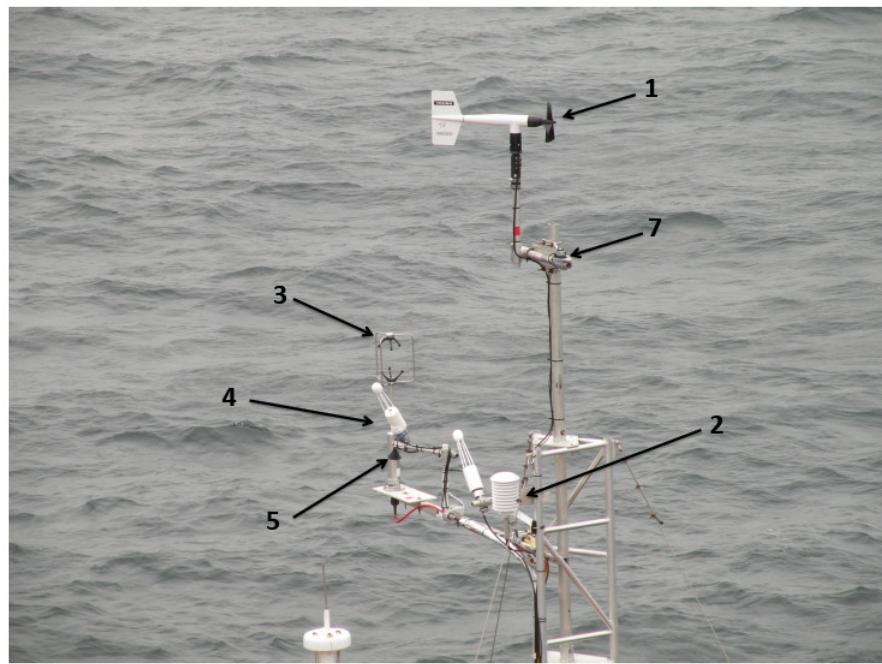


Figure 26: Meteorology and flux program instrument setup. See Table 13 for description of instruments based on the numbers.



Figure 27: Meteorology and flux program instrument setup. See Table 13 for description of instruments based on the numbers.

5.1.3 Dataset Details

Much of the flux tower was fully operational on 3 July 2010. The slow sequence, largely meteorological variables, are scanned at 1s intervals and saved as 1 min averages. Data screening and ship motion correction to wind speed and direction is applied during post-processing. Wind data are screened for times when the apparent wind direction is forward of the ship's wheelhouse. Heavy rime will affect the measurement of wind speed and these periods are also removed from the data set.

The high frequency variables associated with the eddy covariance system are scanned at 0.1 s intervals and are stored as raw data and as 1-minute averages. The raw data are used to compute the fluxes (heat, mass and momentum) over time intervals that can range from 10 min. to 60 min. Frost, rime and aggressive sea spray affect our high frequency measurements of 3D wind and gas concentrations. Periods associated with these events are evident in the data, and need to be removed prior to processing. Fluxes are post-processing computed.

Table 13: Description of instruments shown in figure 26.

Figure 1	Sensor	Variables	Units	Ht from deck (m)	Scan (s)	Specs
					Ave (min)	
1	wind monitor (RM Young 05103)	ws-2D, wd-polar	m/s; °	8.11	1/1	±0.6 m/s ±3° deg
2	temperature/relative humidity probe (Vasaila HMP45C212)	Ta, RH	°C; %	7.2	1/1	Humidity ±2% 0-90% @ 20°C ±3% 90-100% @ 20°C 0.05% RH/°C Temperature ± 0.1 °C
3	3D wind velocity (Gill Windmaster Pro ultra-sonic anemometer)	u,v,w, Ts	m/s; °C	6.36	10 Hz	RMS noise <1% offset <0.01 m/s SOS < 0.5% accuracy
4	LI7500 open path gas analyzer	ρ_v / ρ_c	$\mu\text{mol}/\text{m}^3$ mmol/m	6.82	10 Hz	RMS noise ±0.1 $\mu\text{mol}/\text{mol}$ zero drift 0.1 $\mu\text{mol}/\text{mol}/^\circ\text{C}$ gain drift 0.1%/°C
5 (inlet)	LI7000 closed path gas analyzer	ρ_v / ρ_c	$\mu\text{mol}/\text{m}^3$ mmol/m	inlet at 6.49	10 Hz	RMS noise ±0.1 $\mu\text{mol}/\text{mol}$ zero drift 0.3 $\mu\text{mol}/\text{mol}/^\circ\text{C}$ gain drift 0.2%/°C
Not shown	multi-axis inertial sensor (MotionPak, Systron Donner)	rx,ry,rz accx,accy,accz	°/s; g	4.59	10 Hz	rate <0.004°/s acc <10 μg
6	pyranometer (Eppley, model PSP)	SW_in	W/m ²		2/1	~±5%
7	quantum sensor (Kipp & Zonen, PARLite)	PAR	$\mu\text{mol}/\text{m}^2$		2/1	~±5%
8	pyrgeometer (Eppley, model PIR)	LW_in	W/m ²		2/1	~±10%
Not shown	surface temperature (Apogee SI-111 precision infrared radiometer)	Tsfc	°C	1.6 m	1/1	±0.2 °C accuracy @ -10 to 65 °C ±0.5 °C accuracy @ -40 to 70 °C
Not shown	pressure transducer (RM Young, 61205V)	Patm	kPa		2/1	±0.5 hPa accuracy
9	UV radiation (Kipp & Zonen model UV-S-AB-T)	T_UV, UV_A UV_B	deg C W/m ²		2/1	Daily uncertainty <5%
Not shown	GPS Receiver (Garmin GPS16X-HVS)	lat, lon, SOG COG	°,kts, °		1	Position: <15m, velocity, 0.1 kno

Not shown	Digital compass (Ocean Server OS5000)	H, pitch, roll	$^{\circ}$		1	Precision: 0.5 deg (heading) <1 deg (roll/pitch)
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The Micrometeorology datasets are available at:

\ATMOS\TOWER\MET\

Where daily files are named using the following convention:

proc_MET_YYYY_JDXXX_MMDD.dat

Radiation datasets are available at:

\ATMOS\TOWER\RAD\

Where daily files are named using the following convention:

proc_RAD_YYYY_JDXXX_MMDD.dat

For both MET and RAD files, the naming convention corresponds to date information:

YYYY = year

JDXXX = julian day of year

YYDD = month, day of year

Header information for the MET files is presented in Table 14, and the RAD files in Table 15.

Table 14: Header information for the MET files.

Header	Units	Description
Year		
Month		
Day		
Hour		-DATES/TIMES IN UTC
Min		
Sec		
ProgVer		Datalogger program version used (e.g. foredeck_met_2010_v1.1)
batt_volt_min	V	Minimum datalogger battery voltage, useful for identifying poor datalogger performance
panel_temp_avg	deg C	Temperature of data logger, useful for identifying poor datalogger performance
batt_volt_std		Standard Deviation of battery voltage over 1 minute averaging period, useful for identifying poor datalogger performance
panel_temp_std	V	Panel temperature standard deviation over 1 minute averaging period, useful for identifying poor datalogger performance
t_hmp_avg	deg C	Atmospheric temperature, measurement height ~14m above sea level
rh_hmp_avg	%	Atmospheric relative humidity, measurement height ~14m above sea level
Tsrfc_avg	deg C	Surface skin temperature measured from infrared radiometer
Patm_avg	kPa	Atmospheric pressure
Raw_W_Vel	m/s	Raw wind velocity, uncorrected for ship motion
Raw_W_Dir	deg	Raw wind direction (0/360=wind blowing into front of ship)
Raw_W_std	deg	Raw wind direction standard deviation
t_hmp_std	deg C	Atmospheric T standard deviation over 1 minute averaging period
rh_hmp_std	%	Relative Humidity standard deviation over 1 minute averaging period
Tsrfc_std	deg C	Surface temperature standard deviation over 1 minute averaging period
Patm_std	kPa	Atmospheric pressure standard deviation over 1 minute averaging period
Lat	deg	Latitude of observation (obtained from Ship GPS system)
Long	deg	Longitude of observation (obtained from ship GPS system)
SOG	kts	Speed over ground of ship (obtained from ship GPS system)
COG	deg	Course over ground of ship (obtained from ship GPS system)
Heading	deg	Heading of vessel relative to true north (obtained from ship Gyro system)
SOG_std	kts	Speed over ground of ship standard deviation
COG_std	deg	Course over ground of ship standard deviation
True_W_Vel	m/s	True wind velocity corrected for ship motion, measurement height ~14m above sea level
True_W_Dir	deg	True wind direction relative to true north, measurement height ~14m above sea level
Diag		Diagnostic code word for data processing. If 'NaN', data is ok: 1=tower down, 2=faulty conventional anemometer, 3=faulty infrared radiometer, 4=faulty T/RH probe, 5=faulty P sensor
Pitch	deg	Pitch angle of the tower relative to sea surface (for diagnostic purposes)
Roll	deg	Roll angle of the tower relative to sea surface (for diagnostic purposes)

Table 15: Header information for the RAD files.

Variable	Units	Description
Year		
Month		
Day		
Hour		
Minute		
Second		
Batt_avg	V	Average battery voltage of datalogger (used for some diagnostics)
Panel_T_avg	deg C	Temperature of datalogger
Kdown_avg	W/m ²	Incoming shortwave radiation
Thermopile_avg	W/m ²	Thermopile measurement of long wave radiation sensor (intermediate value for calculating incoming LW)
Tcase_avg	K	Temperature value of long wave radiation sensor (intermediate value for calculating incoming LW)
Tdome_avg	K	Temperature value of long wave radiation sensor (intermediate value for calculating incoming LW)
LWin_avg	W/m ²	Incoming longwave radiation
PARmd_avg	umol/m ² /s	Incoming photosynthetically active radiation measured on top of wheelhouse
T_UV_avg	deg C	Temperature of UV radiation sensor
UV_B_avg	W/m ²	Incoming UV-B radiation
UV_A_avg	W/m ²	Incoming UV-A radiation
PARft_avg	umol/m ² /s	Incoming photosynthetically active radiation measured on the flux tower
Batt_stdev	V	Standard deviation of battery voltage over 1 min averaging period
PanelT_stdev	deg C	Standard deviation of datalogger temperature over 1 min averaging period
Kdown_stdev	W/m ²	Standard deviation of incoming shortwave radiation over 1 min averaging period
Thermopile_stdev	W/m ²	Standard deviation of Thermopile over 1 min averaging period
Tcase_stdev	deg C	Standard deviation of Tcase over 1 min averaging period
Tdome_stdev	deg C	Standard deviation of Tdome over 1 min averaging period
LWin_stdev	W/m ²	Standard deviation of incoming longwave radiation over 1 min averaging period
PARmd_stdev	umol/m ² /s	Standard deviation of incoming PAR measured on top of wheelhouse over 1 min averaging period
T_UV_stdev	deg C	Standard deviation of UV sensor temperature over 1 min averaging period
UV_B_stdev	W/m ²	Standard deviation of incoming UV-B over 1 min averaging period
UV_A_stdev	W/m ²	Standard deviation of incoming UV-A over 1 min averaging period
PARft_stdev	umol/m ² /s	Standard deviation of incoming PAR measured on the flux tower over 1 min averaging period
Latitude	deg	Latitude at time of measurement (from ship GPS data)
Longitude	deg	Longitude at time of measurement (from ship GPS data)

5.2 Passive Microwave Temperature and Water Vapour Profiles

5.2.1 Microwave Profiling Radiometer

A Radiometrics temperature and water vapour 3000A profiling radiometer (TP/WVP3000A) is used to measure the temperature and water vapour within the atmosphere up to 10km using passive microwave radiometry at 22 – 29GHz, and 51 – 59GHz. The TP/WVP3000A is installed on a mount attached to the white container laboratory (the ‘Met Shack’) located directly behind the ship’s wheelhouse, approximately 19m above sea level. The instrument is suspended away from the roof of the shed to ensure that the field-of-view (approximately 15° above the horizon to the left and right to the zenith) is clear of any obstruction (figure 28).



Figure 28: TP/WVP 3000A mounted on the roof of the CCGS Amundsen ‘met shack.’

The radiometer sequentially views atmospheric radiances from the zenith direction in 12 channels - seven in the oxygen band (51-59 GHz) provide information on the temperature profile, and 5 between 22-30 GHz provide information on the humidity profile. The instrument set-up included sensors for surface pressure, temperature and humidity, and a zenith-pointing infrared radiometer (9.6-11.5 μm), which provides cloud-base altitude. The radiometer system rejected periods when the profiles may be erroneous due to precipitation scattering, and/or due to emissions from moisture on the radome filter.

The instrument generates a vertical profile of upper-level air variables including temperature, water vapour density, relative humidity, and liquid water from the surface to an altitude of 10km (Figure 29). The resolution of the measurements varies with height. The resolution of the instrument is 50 m from the surface to an altitude of 500 m, then increases to 100 m from 500 m to 2 km altitude, and is 250 m for measurements from 2 km to 10 km (Note: the height given for 50 m is actually 69 m as the instrument assumes it's at sea level when it's mounted 19m above sea level). In addition, the instrument also measures concurrent basic surface meteorology variables, including pressure, relative humidity, and ambient temperature. A

skyward-looking infrared sensor measures the temperature of the sky. A rain-sensor detects the presence of any precipitation. It should be noted that the fog registered as precipitation during much of the field season. The instrument also calculates integrated column water vapour, and liquid water content. The sampling frequency for all data is approximately one complete profile per minute.

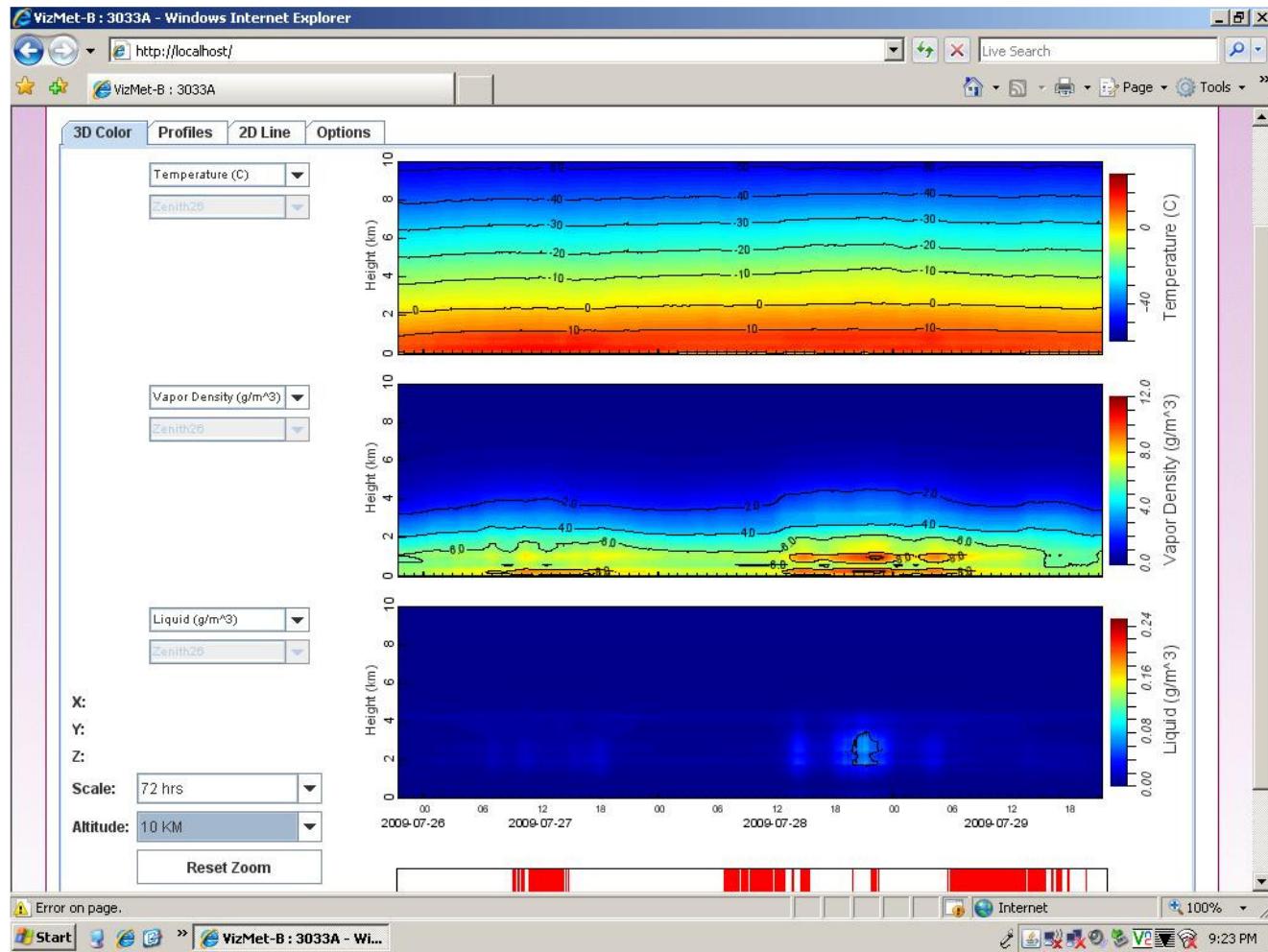


Figure 29: TP/WVP3000A Data example: Temperature (top), water vapour density (middle) and atmospheric liquid content (bottom) are shown. The bar at the bottom shows whether rain was detected or not (red bar).

The calibration of the water vapour profiling process was continuously maintained by hourly tip curves. An external liquid-nitrogen-cooled blackbody was used to intermittently calibrate the temperature profiling process. All channels also viewed an internal black body target every 5 minutes for relative calibration. Temperature and humidity values (0 to 200 m at 50 meter intervals, 500 to 2000 m at 100 meter intervals, and 2000 to 10,000 m at 250 meter intervals) were derived from microwave brightness temperatures using the manufacturer's neural network retrievals that had been trained using historical radiosonde measurements, and a radiative transfer model (Solheim et al., 1998). Historical radiosonde data from Inuvik N.W.T. was used to develop neural network coefficients for the Southern Beaufort Sea Region.

5.2.2 Data Summary

The TP/WVP 3000A was not operational until the beginning of Leg 3. There was an ongoing problem from previous issues regarding an error message “server not ready.” It was determined that the problem was related to a corrupt windows service (cryptography) which the profiler software depends upon to run the profiler server software as daily scheduled task in windows task scheduler. The problem was corrected, and no further problems were noted with the software or hardware. A liquid nitrogen calibration was performed on 27 September 2010, and the operations configuration file was updated.

Datafiles are organized by date into folders named by year and month (yyyy_mm), and are found in the database at:

\ATMOS\MWP\

Datafiles follow the naming convention:

YYYY-MM-DD_HH-MM-SS_tip.csv
YYYY-MM-DD_HH-MM-SS_Lv0.csv
YYYY-MM-DD_HH-MM-SS_Lv1.csv
YYYY-MM-DD_HH-MM-SS_Lv2.csv

Header information for these files is included in the first 6 lines of each data file.

Files with “*.Lv0”, “*.Lv1”, and “*.Lv2” are the raw, first-order processed, and second-order processed datafiles. The “*.tip” files are the daily TIP calibration files used by the radiometer, and are included for reference. The “Lv2” files are the files of interest to the end-user. Records marked 401 – 404 are the key records as they describe the vertical atmospheric profiles of temperature, water vapour density, liquid water, and relative humidity as post-processed by the TP/WVP3000A.

The variable abbreviations are described in Table 16.

Table 16: Microwave Profiling Radiometer “Level 2” file header.

MWP File	Units	
Tamb	K	Surface Ambient air temperature
Rh	%	Surface relative humidity
Pres	Mb	Barometric pressure
Tir	K	Sky temperature (Infrared thermometer)
Rain	n/a	Rain sensor (1 or 0)
Vint	Cm	Vertically integrated water vapour (0 – 10km column total)
Lqint	Mm	Vertically integrated liquid water (0 – 10km column total)
Cldb	km	Cloud base height
Record 401	K	Atmospheric profile temperatures for 0 – 10km
Record 402	g/m ³	Atmospheric integrated vapour profile for 0 – 10km
Record 403	g/m ³	Atmospheric liquid water profile for 0 – 10km
Record 404	%	Atmospheric relative humidity profile for 0 – 10km

5.3 Weather Balloon Temperature and Water Vapour Profiles

5.3.1 Vaisala RS-92G Radiosondes

Balloon launches (figure 30) are conducted to profile low-pressure systems, periods of significant warm or cold-air advection aloft, and for comparison / validation of our TP/WVP3000A microwave profiling radiometer. If a significant cyclone is affecting the region, the sampling interval will be increased to 3-hourly. Due to a limited supply of radiosondes, we constrained our launches to coincide with passing storms, and low pressure disturbances only.



Figure 30: A weather balloon with attached radiosonde, launched from the helicopter deck.

Vertical profiles of temperature, pressure, relative humidity, wind speed and wind direction were obtained using Vaisala RS92G GPS wind-finding radiosondes. The sonde was flown by 300 gm and 200 gm helium-filled balloons at a target ascent rate of 2 to 5 m/s to ensure a good vertical resolution through the boundary layer. An 8-channel uncoded GPS receiver in each sonde automatically detects all satellite signals in visible range. Raw wind vectors are transmitted to the ground station every 0.5 seconds during the flight via digital 1200 baud downlink. All wind computation is done within the ground equipment. Temperature is measured with a THERMOCAP® Capacitive bead, which has a +60.0 C to -90.0 C range, resolution of 0.10C and accuracy of 0.20C up to 50 hPa (most launches terminated before this level). The sensor also has a lag of less than 2.5 seconds in 6 m/s flow at 1000 mb. Pressure is measured with a BAROCAP® Capacitive aneroid. Its measuring range is 1060 mb to 3 mb with a resolution of 0.1 mb and accuracy of 0.5 mb. Humidity is measured with a

HUMICAP® thin film capacitor. Its measuring range is from 0 to 100% relative humidity, with a resolution of 1% relative humidity and accuracy of 3%.

More information on the RS-92G radiosondes is available at:
<http://www.vaisala.com/weather/products/rs92.html>

The sensor also has lag of 1 second in 6 m/s flow, 1000 mb pressure and +200C. The temperature, pressure and humidity sensors are collectively sampled at 7 times per 10 seconds. All raw data from the sonde are processed at the ground station through a DigiCORA/MARWIN processor. The DigiCORA is connected to a computer, where data can be viewed in real time throughout the launch and where the data is archived. PILOT and TEMP codes are also produced after the launch terminates. PILOT and TEMP codes, as well as raw and edited measurements were archived for each launch. The edited data is stored in a text file in delimited columns.

Before launch, the radiosonde's temperature, pressure and humidity sensors are calibrated using the Vaisala ground station calibration unit. Surface meteorological observations are also noted and recorded for each launch. Starting meteorological conditions are input into the sounding including: sea level pressure, air temperature, relative humidity, and wind speed and direction.

5.3.2 Data Summary

There were 13 balloon launches from 12 August to 07 October 2010 (Table 17).

Table 17: Balloon launch summary for 2010.

Date (GMT)	Time (GMT)	Tair °C	RH (%)	P (mb)	Wind speed (kts)	Wind dir. (°true)
20100925	0600	-0.2	89	1008.1	14	020
20100925	1800	1.0	71	1000.77	23	190
20100926	0600	0.0	66	1003.13	5	320
20100926	1800	0.8	78	1005.22	9	265
20100927	0600	-1.6	79	1006.10	11	040
20100927	1800	-5.2	99	1003.18	8	207
20100928	0600	-3.6	96	1000.73	7	165
20100929	1800	-2.7	89	1000.16	5	154
20100930	1800	-0.8	68	1008.99	20	287
20101001	1800	0.7	87	1013.75	7	265
20101002	1800	0.0	98	1000.60	28	066
20101004	1800	-3.9	74	1016.41	33	087
20101005	1800	-6.3	74	1006.40	27	080

Data is transmitted at a rate of one message per second via VHF radio (~400.00MHz). Each data message reports a value for pressure, temperature and humidity data (raw PTU data). GPS strings are also transmitted, and are used to calculate upper-level wind speed and direction. All raw PTU and GPS data is used to generate an ensemble of time series data with variables and information information presented in Table 18.

Table 18: Variable denotation header found within radiosonde data files.

Record Name	Unit	Divisor	Offset	Description
Time	sec	1	0	Time
Pscl(ln)	Ln	1	0	(internal)
T(K)	K	10	0	Air Temperature
RH(%)	%	1	0	Relative Humidity
v(m/s)	m/s	-100	0	North-south orthogonal wind component
u(m/s)	m/s	-100	0	East-west orthogonal wind component
Height(m)	m/s	1	30000	Height above ground
P(hPa)	hPa	10	0	Barometric Pressure
TD(K)	K	10	0	Dewpoint temperature
MR(g/kg)	g/kg	100	0	Mixing ratio
DD(dgr)	dgr	1	0	Direction of wind
FF(m/s)	m/s	10	0	Wind speed
AZ(dgr)	dgr	1	0	Bearing to sonde from ground station
Range(m)	M	0.01	0	Range to sonde from ground station
Lon(dgr)	dgr	100	0	Longitude of sonde
Lat(dgr)	dgr	100	0	Latitude of sonde
puKey(bitfield_	bitfield	1	0	Internal
UsrKey(bitfield)	bitfield	1	0	Internal
RadarH(m)	m/s	1	30000	Radar reflector range to sonde (not used).

21 radiosonde profiles were flagged with quality assurance issues. The 20 that passed quality assurance are organized into folders by date, and are available in the database at:

\ATMOS\SONDE\yyyy_mm\

5.3.3 Data Summary

A data visualization sample for an atmospheric sounding (Figure: 31).

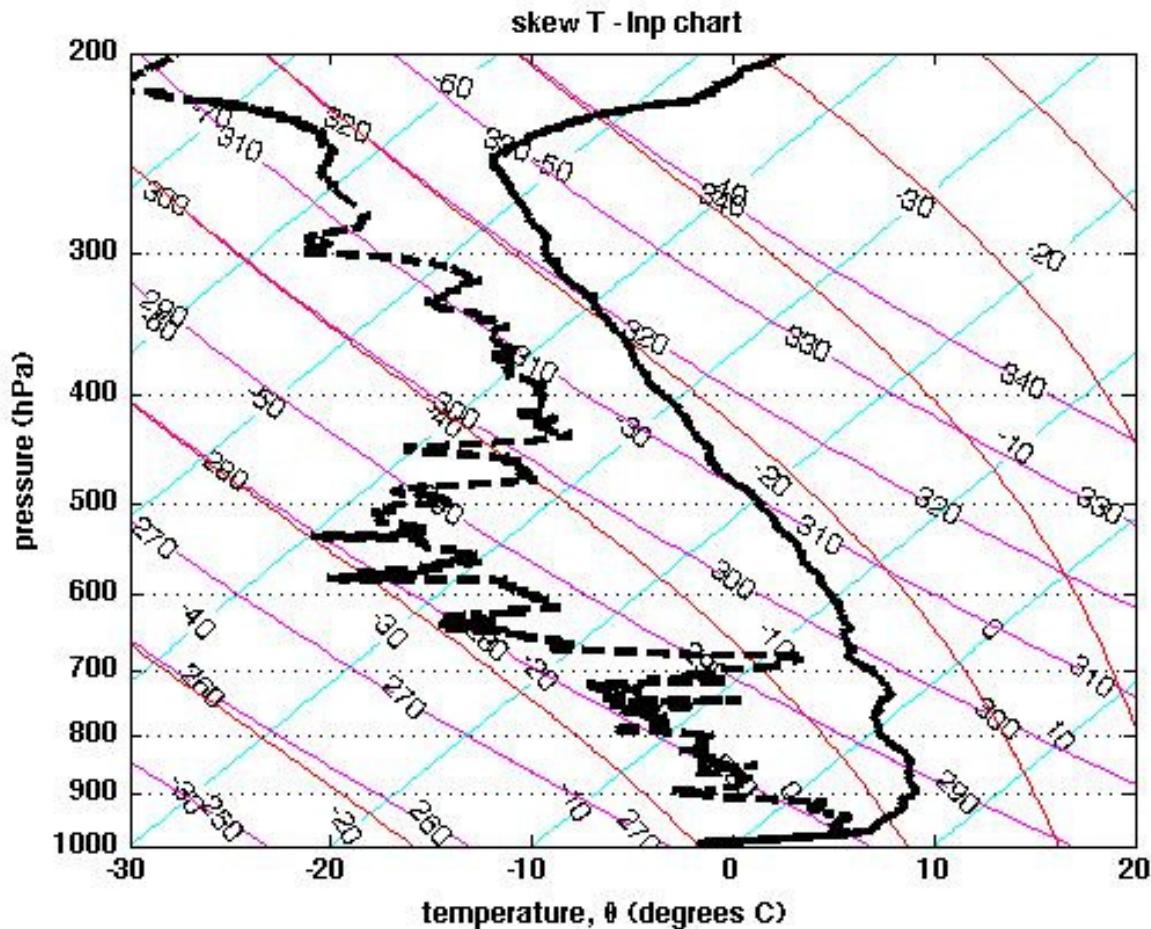


Figure 31: Air temperature (solid) and dewpoint temperature (dashed) are presented on a SkewT-LnP chart.

5.4 Cloud Base Height

5.4.1 Vaisala CT25K Ceilometer

The Vaisala CT25K laser ceilometer (figure 32) measures cloud heights and vertical visibilities using pulsed diode laser LIDAR (Light Detection And Ranging) technology, where short powerful laser pulses are sent out in a vertical or near-vertical direction. The laser operates at a centre wavelength of 905 ± 5 nm, a pulse width of 100 ns, beamwidth of ± 0.53 mrad edge, ± 0.75 mrad diagonal and a peak power of 16 W. The manufacturer suggested measurement range is 0 – 25,000ft (0 – 7.5 km), however, it has been found that high, very visible cirrostratus cloud (~18-20 kft) are consistently undetected by the unit (Hanesiak, 1998). The vertical resolution of the measurements is 50 ft, but decreases to 100 ft after ASCII data file conversion. The reflection of light backscatter caused by haze, fog, mist, virga, precipitation, and clouds is measured as the laser pulses traverse the sky. The resulting backscatter profile (i.e., signal strength versus height) is stored, processed and the cloud bases are detected. Knowing the speed of light, the time delay between the launch of the laser pulse and the backscatter signal indicates the cloud base height. The CT25K is designed to detect three cloud layers simultaneously, given suitable conditions. Besides cloud layers, it detects whether there is precipitation or other obstruction to vision. No adjustments in the field are needed. Output files were created hourly by the system and are in ASCII format. The ceilometer measurements were made in conjunction with all-sky camera measurements throughout the entire observational period. Ceilometer data was collected continuously throughout the entire 2010 cruise of the CCGS Amundsen.

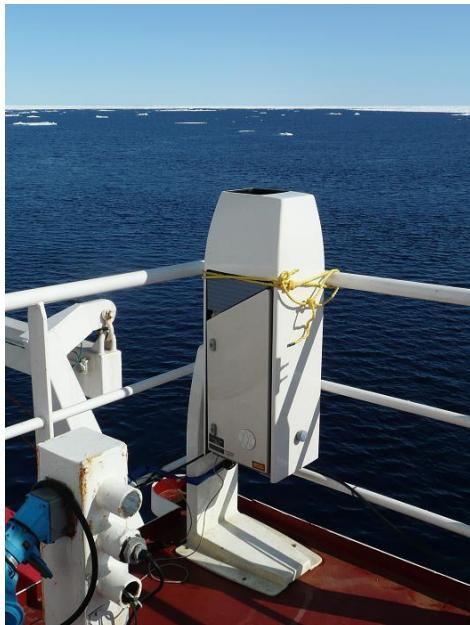


Figure 32: Vaisala CT25K ceilometer mounted at 90° behind the wheelhouse.

5.4.2 Data Summary

The ceilometer was running continuously from 01 July 2010 – 19 October 2010, and daily data files are available for the entire period.

Ceilometer files are available as processed ASCII daily files.

The Processed files are available at

\ATMOS\CEIL\PROCESSED\

Daily filenames follow the naming convention:

CEIL_YYYY_MM_DD.csv

The file header information is defined in Table 19:

Table 19: Ceilometer *.CSV file header

Header	Description	Units
J_day	Julian day of year	n/a
Year	Year	n/a
Month	Month	n/a
Day	Day	n/a
Hour	Hour	n/a
Min	Minute	n/a
Sec	Seconds	n/a
Lat	Latitude	decimal deg (DD.DDDDD)
Lon	Longitude	decimal deg (DDD.DDDDD)
SOG	Speed over ground	Nm / hr
COG	Course over ground	Degrees (°)
Layer1	Cloud layer base height 1	Ft
Layer2	Cloud layer base height 2	Ft
Layer3	Cloud layer base height 3	Ft

5.4.3 Data Visualization

Ceilometer data for September 2010 is visualized in figure 33.

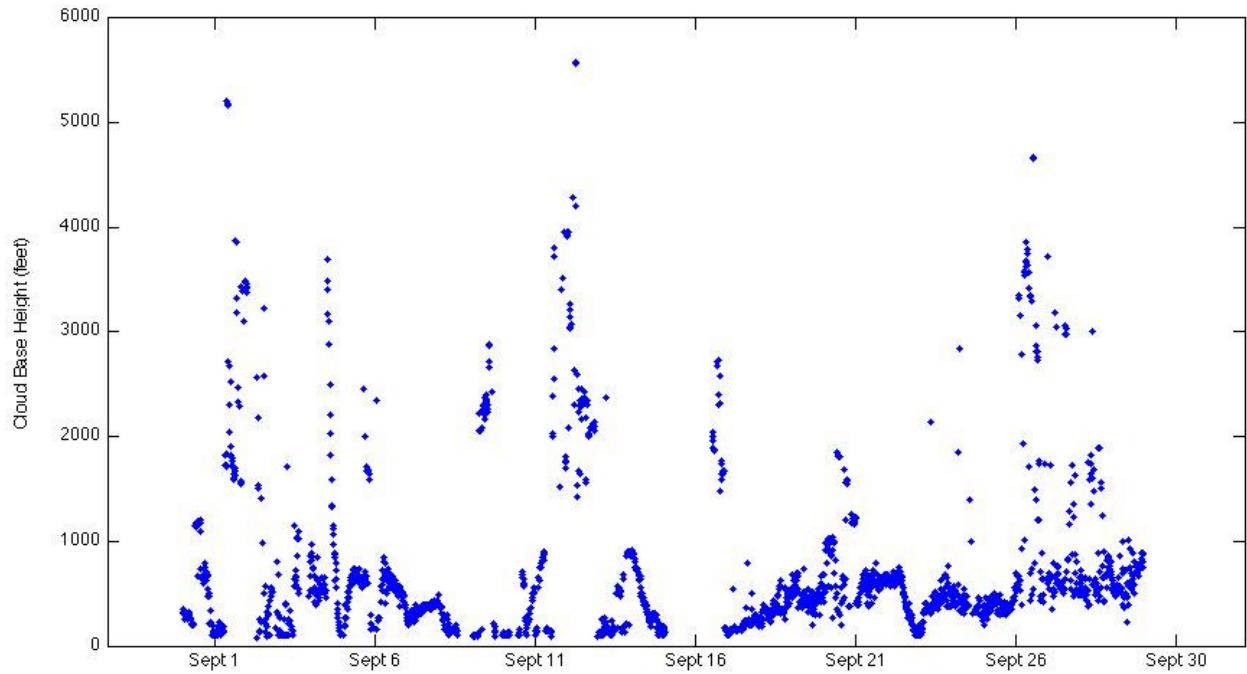


Figure 33: Detected ceilometer cloud-base heights for September 2010.

5.5 All-Sky Camera Imagery

5.5.1. Instrumentation

The all-sky camera system takes images of the sky and cloud cover. The system consists of a Nikon D-90 camera outfitted with fish-eye lenses with a viewing angle of 160 degrees, mounted in a heated weather-proof enclosure. The camera is programmed to take pictures using an external intervalometer set at 15-minute intervals, or 96 images per day. The system is mounted in a small 'crow's nest' immediately above the ship's wheelhouse (figure 34).

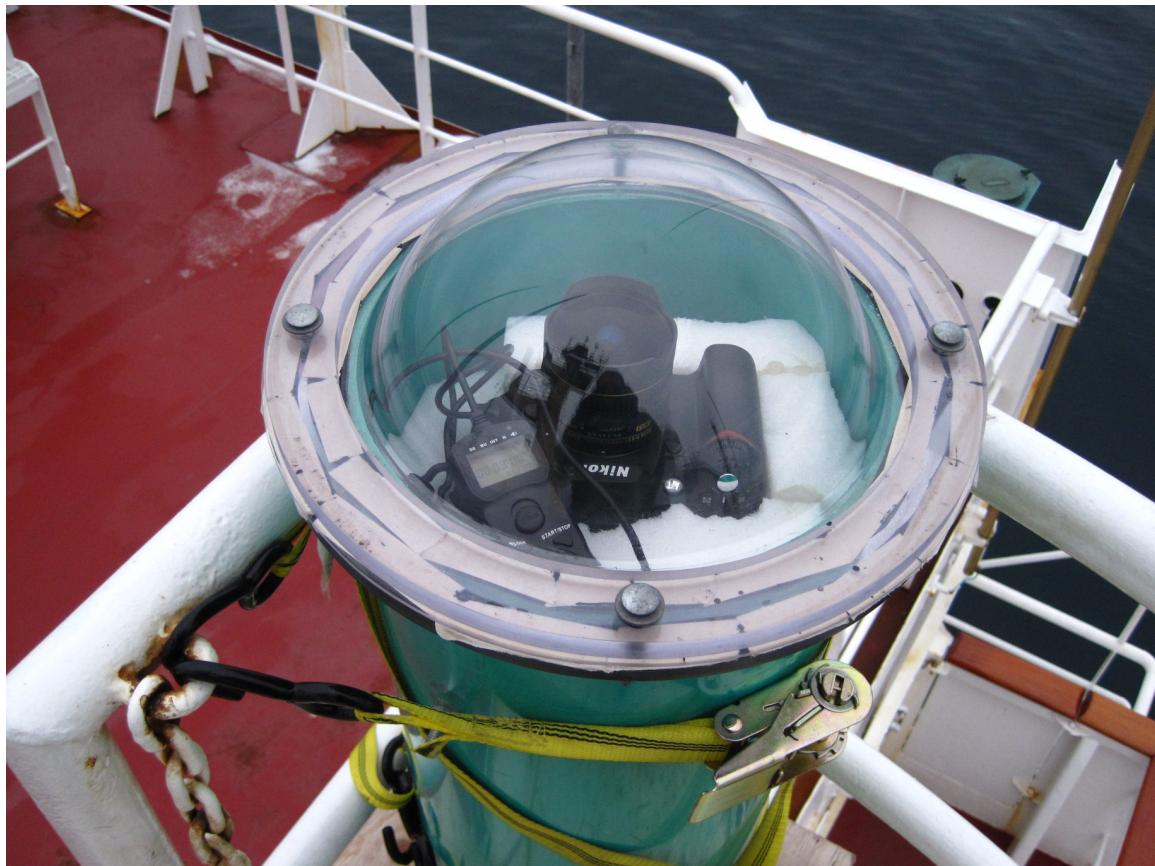


Figure 34: Nikon D-90 Camera with fisheye lenses attached in a weatherproof enclosure.

Imagery collection started on 04 July 2010, and was continuous through to 22 October. Gaps in the data are due to routine maintenance and setting adjustments due to the changing light. The camera was set to have an aperture of f-12 with a variable exposure time. This allowed for low light or night time images to be taken.

All-sky imagery is found in the database at:

\ATMOS\ALLSKY\YYYY-MM-DD\

5.5.2 Data Visualization

A example all-sky image showing 6/8 broken cloud cover is shown in figure 35.



Figure 35: An all-sky camera image showing partial cloud coverage.

5.6 Manual Meteorological Observations

5.6.1 Instrumentation

Manual meteorological observations were conducted at 3-hour intervals throughout the entire 2010 field season, except for at night when observers were sleeping. There is a gap in observations starting from 26 August to 22 September 2010 due to no observers onboard at the time. Observations included current conditions with relation to precipitation type and intensity, visibility, cloud cover (octets), and sea ice coverage (tenths). Basic meteorological values were read and recorded from the onboard weather station, which is owned and operated by the Meteorological Service of Canada. Visibility, cloud octets, sea ice concentration, and precipitation type and intensity observations are subjective based on the observer. If the cloud coverage was not 100% it was not recorded at 8/8, similarly if the coverage has even 1% of clouds the cloud fraction was not recorded as 0/8.

The CCGS *Amundsen* is equipped with an AXYS Automated Voluntary Observation Ship (AVOS), with all sensors located on the roof of the wheelhouse. The AVOS is an interactive environmental reporting system that allows for the hourly transmission of current meteorological conditions to a central land station via Iridium satellite telemetry. Temperatures (air and sea surface), pressure, relative humidity (RH), wind speed, wind direction, and current GPS location are updated every ten minutes and displayed on a computer monitor located in the wheelhouse of the ship. The AVOS deploys a Rotronics MP 101A sensor for temperature and RH, with a resolution of 0.1°C and an accuracy of $\pm 0.3^{\circ}\text{C}$, and a $1\% \pm 1\%$ accuracy for temperature and RH, respectively. Atmospheric pressure was obtained from a Vaisala PTB210 sensor with a 0.01mb resolution and an accuracy of ± 0.15 mb. Wind speed and direction is collected from an RM Young 05103 anemometer, accurate to $\pm 3^{\circ}$ in direction and ± 0.3 m/s.

5.6.2 Data Summary

Table 20: Parameters recorded by the observer.

Parameter	Units
Date	UTC
Time	UTC
Latitude	decimal degrees
Longitude	decimal degrees
Temperature	°C
Relative Humidity	%
Wind Speed	Kts
Wind Direction	°
Precipitation Type	snow, rain etc
Precipitation Intensity	Heavy, moderate, light etc.
Visibility	Nm
Cloud Fraction	Octets
Sea Ice Concentration	Tenths

The manual meteorological observations are available in the database at :

\ATMOS\MANOBS\

SECTION SIX: OTHER CRUISE DATA

6.1 GPS Position

NMEA RMC Strings collected by the CCGS *Amundsen*'s DGPS system for the entire field season are processed into daily files, at minute and second intervals.

ASCII files (*.dat extension) are found in the database for 1 minute resolution at:

\OTHER\NAV\GPS_RMC\RMC_DAILY_1min\

and for 1 second resolution at:

\OTHER\NAV\GPS_RMC\RMC_DAILY_1sec\

File naming convention is as follows for 1 minute resolution:

\1min_RMC_2010_JDxxx_MMDD.dat

and for 1 second resolution:

\RMC_2010_JDxxx_MMDD.dat

Where: JDxxx corresponds to the julien day, and MMDD is month and day.

File header:

(Dates and times are in UTC).

Year:

Month:

Day:

Hour:

Min: Minute

Sec: Second

Lat: Latitude (decimal degrees)

Lon: Longitude (decimal degrees)

SOG: Speed over ground (nm / hr)

COG: Course over ground (degrees)

SOG_ST: (standard deviation of speed over ground

COG_ST: (standard deviation of course over ground

6.2 Gyronometer

The CCGS *Amundsen*'s Gyronometer provides ship heading.

ASCII files (*.dat extension) are found in the database at 1 minute resolution:

\OTHER\NAV\GYRO\GYRO_DAILY_1min\

and at 1 second resolution:

\OTHER\NAV\GYRO\GYRO_DAILY_1sec\

File naming convention is as follows for 1 minute resolution:

\1min_GYRO_2010_JDxxx_MMDD.dat

and for 1 second resolution:

\GYRO_2010_JDxxx_MMDD.dat

Where: JDxxx corresponds to the julien day, and MMDD is month and day.

File header:

(Dates and times are in UTC).

Year:

Month:

Day:

Hour:

Min: Minute

Sec: Second

Heading: heading (degrees)

6.3 Science Logs

The bridge staff of the CCGS *Amundsen* kept a written log of all science activities. For each science entry in the log, date (LST and GMT), geographic position (degree, decimal-minutes, and decimal degrees), depth, and basic meteorological variables including air temperature, relative humidity, wind speed and direction, and sea ice concentration are recorded. The science logs are also available in this document in Appendix A.

These science logs are also available as digital files in the database at:

\OTHER\SCIENCE LOGS

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09																
CA05 MAP-09	25/09/2010	18 19	70°58.27N	134°46.04W	204	RECUPERATION LF 7	303	16	330	-0.1	5.3	1001.3	98	-		
CA05 MAP-09	25/09/2010	19 13	70°55.85N	134°58.62W	204	RECUPERATION LF 4	345	14	330	-0.5	5.4	1002.1	81	-		
CA05 MAP-09	25/09/2010	20 40	70°56.8N	134°18.6W	237	Ligne de Sondage BP 250	172	16	338	-0.1	5.55	1003.35	78	-		
CA05 MAP-09	25/09/2010	22 22	70°44.19N	135°17.36W	057	Ligne de Sondage 500	97	9	318	0.5	5.62	1002.91	65	-		
CA05 MAP-09	25/09/2010	00 30	70°57.484N	134°14.243 W	232	BALLOON METEO	181	01	240	0.1	5.57	1003.7	66	-		
CA05 MAP-09	26/09/2010	08 00	70°45.54N	135°08.94W	315	ROSETTE HF4	77	6	323	0.5	6.17	1002.0	77	-		
CA05 MAP-09	26/09/2010	09 33	70°53.33N	135°22.23W	300	MARU HF5	524	8	265	5.03	0.5	1004.6	75	-		
CA05 MAP-09	26/09/2010	11 55	71°06.042N	135°23.01W	082	Morus HF4	641	6	259	1.3	3.99	1004.3	78	-		
CA05 MAP-09	26/09/2010	12 15	71°03.877N	134°22.204W	057	AREA MAPPING	519	9	280	0.8	4.2	1005.2	79	-		
CA05 MAP-09	26/09/2010	12 38	71°06.43N	134°40.03W	058	BALLOON METEO	499	5	275	0.8	4.3	1005.3	79	-		
CA05 MAP-09	26/09/2010	14 21	71°10.17N	134°40.00W	054	MAPPING Fin	599	7	340	0.2	4.33	1005.5	88	-		
CA05 MAP-09	27/09/2010	00 00	72°40.56N	130°37.74W	040	BALLOON Meteo	1531	5	190	-1.8	1.2	1005.95	89	Frazil		
CA05 MAP-09	27/09/2010	22 13	74°23.774N	129°08.157W	107	E.M Scan	404	7	160	-4.1	0.25	1000.93	93	8/10		
CA05 MAP-09	28/09/2010	00 35	74°23770N	129°09.400W	035	BALLOON Meteo	411	8	164	-3.8	0.23	999.9	97	9/10		
CA05 MAP-09	28/09/2010	09 05	74°21.84N	129°10.15W	073	Equipe sur la glace	428	6	120	-3.3	0.18	997.7	76	9/10		
CA05 MAP-09	28/09/2010	10 00	74°21.66N	129°11.05W	073	Fin d	428	6	161	-3.5	0.87	1000.2	88	9/10		
CA05 MAP-09	28/09/2010	12 11	74°24.46N	129°09.55W	022	BALLOON Meteo	287	6	156	-3.9	1.24	1000.14	93	3/10		
CA05 MAP-09	28/09/2010	17 01	74°40.28N	128°32.55W	080	ROSETTE ↓	379	6	180	-4.1	1.32	1000.6	96	8/10		
CA05 MAP-09	28/09/2010	17 35	74°40.17N	128°32.31W	088	ROSETTE ↑	385	7	150	-4.0	1.25	1000.7	97	8/10		
CA05 MAP-09	28/09/2010	19 29	74°39.93N	128°15.50W	281		378	2	061	-3.5	-0.45	1000.7	97	8/10		
CA05 MAP-09	28/09/2010	20 43	74°39.93N	128°15.50W	281	Fin d	378	2	061	-3.5	-0.45	1000.7	97	8/10		
CA05 MAP-09	29/09/2010	16 37	79°37.25N	128°20.864W	355	Scatterometer Scan	381	5	227	-5.8	1.71	1600.83	99	7/10		
CA05 MAP-09	29/09/2010	11 25	74°36.96N	128°21.205W	000	Début n enchantionnage eun glace	379	2	213	-5.3	1.79	1000.97	99	8/18		
CA05 MAP-09	29/09/2010	14 45	74°36.9N	128°21.3W	000	Fin echant. l6n Glace	380	8	220	-5.8	2.21	1001.20	99	9+/10		
CA05 MAP-09	29/09/2010	15 30	74°45.34N	127°56.62W	130	Début echan. Glace	367	9	234	-4.1	2.39	1001.80	99	9+/10		
CA05 MAP-09	29/09/2010	11 47	74°45.49N	127°54.22W	130	Fin echan. Glace	367	8	230	-8.9	2.08	1002.44	95	9+/10		
CA05 MAP-09	30/09/2010	11 20	71°55.86N	125°20.52W	268	Equire de calibération a Terre a Sachs Harbour	17	22	277	-0.8	5.16	1006.36	67	-		
CA05 MAP-09	30/09/2010	13 20	71°55.875N	125°29.513W	291	BALLOON Meteo	24	20	282	-1.1	5.07	1010.31	66	-		
CA05 MAP-09	30/09/2010	18 37	71°47.183N	126°29.969W	330	SECCHI↓	3.8	10	280	-1.4	5.56	1013.91	67	-		
CA05 MAP-09	30/09/2010	18 39	71° 47.191N	126°29.931W	347	SECCHI↑	3.7	6	273	-1.5	5.55	1014.14	67	-		
437	30/09/2010	18 40	71°47.193N	126°29.943W	002	PNF ↓	315	6	278	-1.5						
437	30/09/2010	18 47	71°47.184N	126°29.916W	016	PNF ↑	316	7	260	-1.5						
437	30/09/2010	19 36	71°47.178	126°29.762W	252	CA - 16 - 10	318	13	240	-1.4						
437	30/09/2010	19 48	71°46.948N	126°29.415W	050	Triangulation CA -16-10	321	10	270	-1.3						
437	30/09/2010	20 02	71°47.437N	126°29.364W	030	Triangulation CA -16-10	304	11	263	-1.6						

DULLEN	3/10/2010	23 45	70°53.26N	134°27.80W		MAPPING FIN Section 3		23	085	-1.3	6.89	1008.7	-
PINGOS													
DULLEN	4/10/2010	00 45	71°05.03N	134°17.40W	304	MAPPING debut ner Beaufort	481	25	071	-1.4	6.77	1011.73	76
PINGOS													
DULLEN	4/10/2010	03 08	71°14.768N	134°34.798W	035	MAPPING FIN ner Beaufort	860	28	075	-1.7	6.42	1012.73	80
PINGOS													
DULLEN	4/10/2010	12 52	71°47.20N	130°00.84W	092	BALLOON meteo	284	35	099	-3.4	5.87	1015.5	74
PINGOS													
DULLEN	5/10/2010	13 24	71°55.915N	125°21.454W	086	BALLOON meteo	16	27	083	-6.5	5.12	1007.8	91
PINGOS													
408	6/10/2010					ROSETTE ↓							-
408	6/10/2010					ROSETTE ↑							-
408	6/10/2010	14 35	71°19.05N	127°35.60W	025	↓ P.N.F	205	16	048	-4.2	6	1008.2	81
408	6/10/2010	14 40	71°19.05N	127°35.68W	016	↑ P.N.F	207	14	044	-4.9	6	1008.1	79
408	6/10/2010	14 40	71°19.06N	127°35.69W	014	SECCHI ↓	208	15	042	-4.9	6	1008.1	79
408	6/10/2010	14 43	71°19.06N	127°35.73W	013	SECCHI ↑	205	13	034	-4.9	6	1008.1	79
408	6/10/2010	15 10	71°19.05N	127°35.54W	030	DEBUT MOUILLAGE CA05-10	205	15	056	-5.2	6.14	1008.1	79
408	6/10/2010	15 37	71°19.05N	127°35.59W	031	FIN mouillage, CA05-10	206	10	025	-11	6.18	1008.2	78
408	6/10/2010	15 51	71°19.662N	127°36.212W	147	Trinagulation CA 05 - 10, 427 m	702	16	030	-4.0	6.19	1008.15	79
408	6/10/2010	15 56	71°18.912N	127°35.394W	096	Trinagulation CA 05 - 10, 419 m	707	20	029	-4.0	6.19	1008.15	79
408	6/10/2010	16 01	71°19.230N	127°35.514W	318	Trinagulation CA 05 - 10, 422 m	709	18	044	-4.7	6.19	1007.98	82
408	6/10/2010	20 40	71°00.22N	126°04.36W	030	Deployment CA 08-10	392	19	011	-3.5	5.59	1007.22	88
408	6/10/2010	21 14	71°00.279N	126°04.275W	071	CA-08-10 deploye	394	18	022	-3.6	5.50	1007.57	88
408	6/10/2010	21 47	71°00.025N	126°04.704W	193	Triangulation Pos 3	399	19	027	-3.6	5.5	1007.37	88
408	6/10/2010	22 00	71°01.050N	126°02.233W	036	ROSETTE PP, NUTS ↓	393	14	015	-3.5	5.44	1007.15	93
408	6/10/2010	22 41	71°01.70N	126°07.629W	020	ROSETTE PP, NUTS ↑	396	13	025	-3.9	5.42	1007.12	94
408	6/10/2010	22 56	71°00.987N	126°02.136W	123	TUCKER NET ↓	397	15	020	-4.1	5.43	1007.59	94
408	6/10/2010	23 17	71°00.618N	126°00.009W	109	TUCKER NET ↑	393	16	020	-4.2	5.40	1007.69	96
408	6/10/2010	23 27	71°00.529N	125°59.767W	90	BONGO NET ↓	397	16	020	-4.3	5.39	1007.71	95
408	6/10/2010	23 35	71°00.473N	125°59.784W	114	BONGO NET ↑	394	14	015	-4.3	5.38	1007.73	95
408	6/10/2010	23 57	71°00.44N	125°59.72W	52	MONSTER NET ↓	397	13	018	-4.1	5.38	1007.8	94
408	7/10/2010	00 25	71°00.42N	125°59.46W	47	MONSTER NET ↑	394	13	024	-4.1	5.39	1007.9	95
408	7/10/2010	00 54	71°00.48N	125°59.85W	5	ROSETTE ↓	395	13	013	-4.1	5.4	1008.2	96
408	7/10/2010	01 12	71°00.23N	126°00.23W	10	ROSETTE ↑	396	12	000	-4.3	5.41	1008.3	96

APPENDIX B: DATA CHART

